

dpv evolution

User Manual

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User Manual Part

DPV Evolution

Edition

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- Edition 2, April 2014

The material contained in this document is provided “as is” and is subject to change without notice in future editions.

Overview

Orientation:

- Table of contents at the front of the manual
- Index at the rear of the manual

This manual contains the following sections:

- “Safety”
- “Product description”
- “Installation”
- “Maintenance”
- “Operation”

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1. SAFETY SUMMARY

The following safety precautions should be observed during all phases of operation of the DPV Evolution.

Tecnar Automation Ltd. assumes no liability for customer's failure to comply with these precautions or with specific warnings elsewhere in this manual.

1.1 GENERAL PRECAUTIONS

- Do not use a noisy or overloaded power line
- Supply cooling / cleaning air at 2.0-2.8 bar (30-40 psi) to sensor head
- Use only original spare parts

1.2 AUTHORIZED USE

DPV Evolution is intended for use solely for thermal spray process monitoring and control. Any other use is regarded as unauthorized.

Also, this manual should be read before the use of the DPV Evolution is authorized and a copy of it should be kept near the equipment.

DPV Evolution has been designed and manufactured according to state-of-the-art technology and recognized safety regulations. However, unauthorized use can result in danger to the operator or third parties' body or even life and/or in damage to the product itself or other machinery.

1.3 SAFETY SIGNS

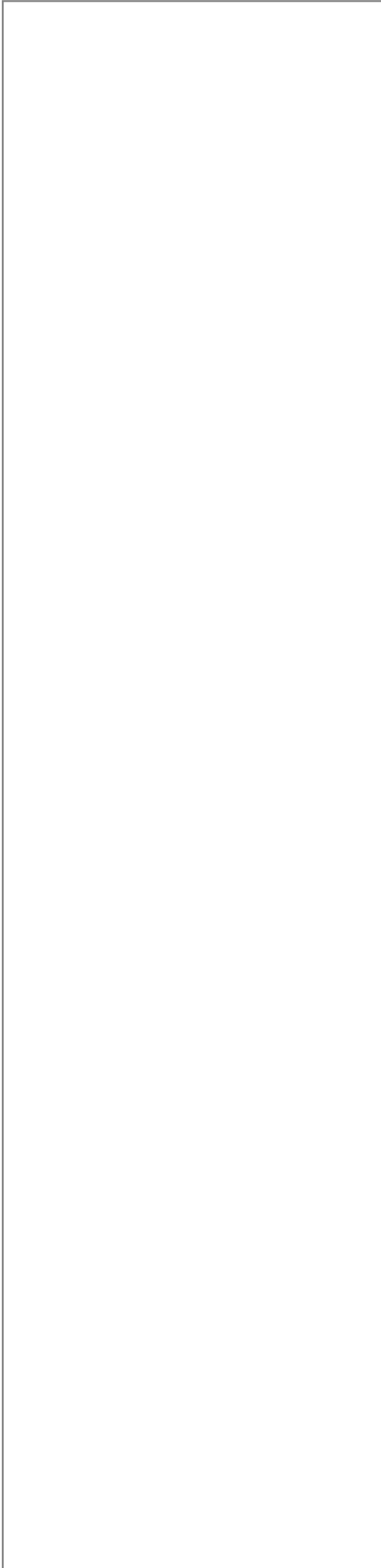
Signs such as the two examples below indicate particular hazards or risks to consider when operating the DPV Evolution.

The danger sign denotes a hazard. It warns about dangers which could result in serious personal injury or even death.

The caution sign denotes a hazard. It warns about dangers which could result in minor personal injury or equipment damage.

WARNING

CAUTION



2. PRODUCT DESCRIPTION

The DPV Evolution is an optical sensing device used in the field of thermal spraying processes. Based on a patented technology developed by the National Research Council of Canada, this system uses infrared pyrometry along with a dual slit optical device to perform in-flight diagnostics on individual particles. The DPV Evolution system provides simultaneous & precise temperature, velocity and diameter measurements of up to 800 individual particles/sec depending on spraying conditions. Values of these parameters averaged over an adjustable measurement period are continuously recorded and displayed.

The reproducibility of coatings obtained by spraying processes strongly depends on the ability to monitor and control key variables of the process. Present state of the art technology is based on the control and monitoring of torch zone variables such as arc current, arc voltage, arc gas flow rates, powder feed rate, powder carrier gas flow rate and net plasma energy. Some of those variables simply cannot be monitored. However, the DPV Evolution provides real-time monitoring of parameters proper to the particle plume itself. Those parameters (temperature, velocity & diameter of particles, and also particle flow rate) are among the most critical ones in the projection zone, and up to now, they could not be continuously measured and controlled in a typical industrial production environment; the DPV Evolution offers that possibility.

The characterization of individual particles during the projection, as performed by the DPV Evolution, is the most relevant tool to ensure rapid detection of problems during the process and consequently, to improve reliability and reproducibility of the thermal coatings obtained. Based on results and analysis provided by the DPV Evolution, various feedback strategies for the torch zone parameters can be developed, leading to significant cost reduction in terms of test pieces and wasted production.

Note

The Main controller contains all necessary optical & electronics components. It also features an industrial, touch screen computer.

The Fiber Cable carries light from the particles to the pyrometer inside the Main Controller for analysis.

The XY Scanning unit allows for computer-controlled, 2D cross-sectional mapping of the spray plume.



2.1 MAIN COMPONENTS

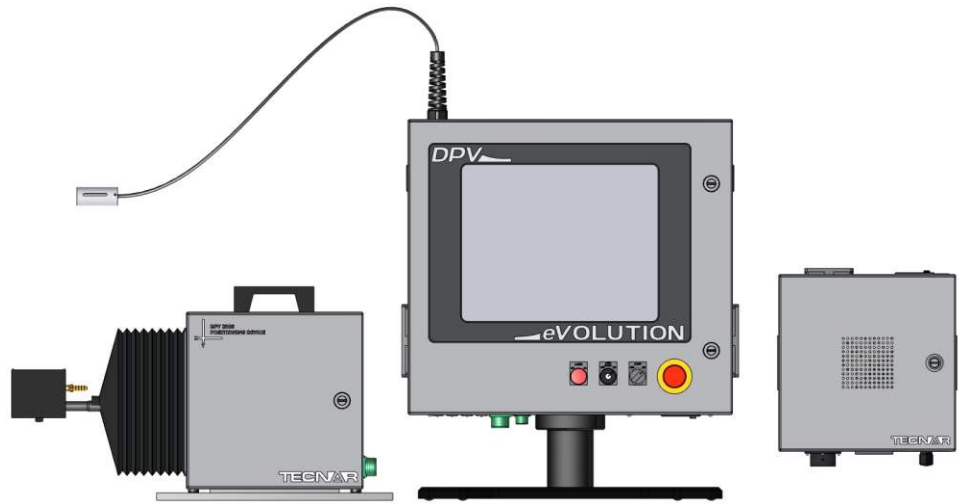


FIGURE 1 DPV EVOLUTION MAIN COMPONENTS

2.1.1 THE SENSING HEAD

The optical sensor consists of a special multi-elements IR relay lens corrected for both geometrical and wavelength aberrations. A protective window is installed at the front of the lens (the closest to the plasma). The lens is coupled to an optical fiber bundle consisting of one 400µm fiber surrounded by 2 other fibers used for alignment purposes. An optical two-slits photomask (schematically shown in Figure 2 Two-Slits mask) is inserted between the lens and the central fiber, in contact with the latter. Because of this photomask, a particle passing in front of the sensor will generate a twin-peaks signal as illustrated in Figure 2 Two-Slits mask.

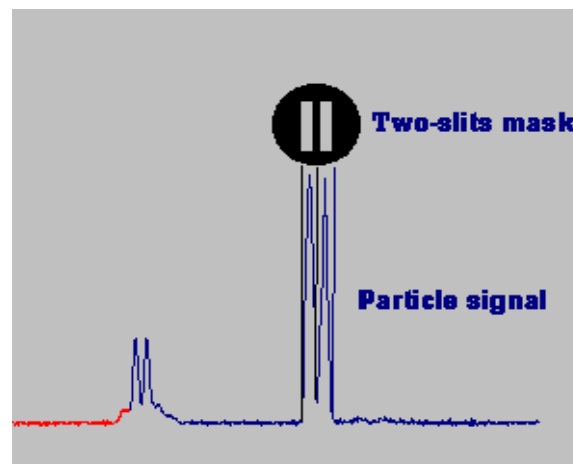
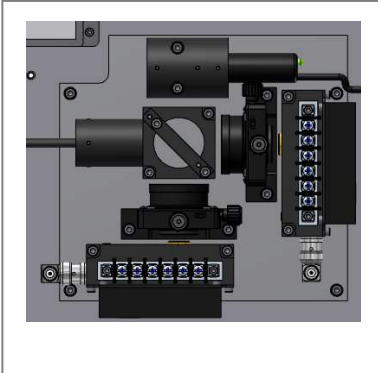


FIGURE 2 TWO-SLITS MASK

A particle will generate a valid signal only when its trajectory is totally included within the surface of both slits and the depth of field of the relay



lens. We refer to the product (slit area)*(depth of field) as the *measurement volume* of the DPV Evolution.

2.1.2 THE DETECTION MODULE

The signal collected by the lens near the plasma/flame is transmitted through the optical fiber bundle to the Detection Module. The optical cable splits before entering the detection module. One end of the cable contains the alignment fibers while the other one contains the central 400µm fiber. Light transmitted through the central fiber first passes through a custom-made dichroic mirror and through interference band-pass filters. It is then imaged on two Si photodetectors. Signals from the photodetectors are linearly amplified and filtered. Basically, the dichroic mirror splits the IR optical spectrum; any wavelength under 900 nm is reflected (in our case, light is going to detector #1) while the rest of the spectrum is passing through the dichroic mirror towards detector #2.

Another fiber could be added (as an option) to the bundle with the CPS (Cold Particles Sensor) option. The fiber is used for illumination of the particles.

2.1.3 THE CONTROL MODULE

Signals from the photodetectors are transmitted to the Control Module to be digitized and analyzed by the software (described in section 5. *Operation*). The control module consists of an industrial grade PC equipped with a touch screen display and a high speed digitizing board for data acquisition.

Front panel

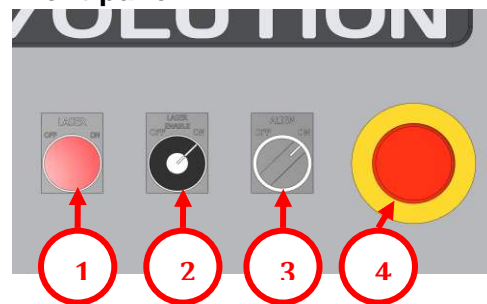


FIGURE 3 CONTROL MODULE FRONT PANEL

■ Laser Control (1) *CPS OPTION ONLY*

This push button is used to control the laser source used for cold particles characterization experiments. Pressing the button will activate or deactivate the laser. The laser is active when the button's light inside is ON.

■ Laser safety switch (2) *CPS OPTION ONLY*

The laser safety switch is a safety component. The laser source can only be activated when the key is inserted and in the ON position. When not in use, it is recommended to remove the safety key, thus preventing anyone that has not been properly trained from using the laser.

▪Alignment switch (3)

The alignment switch is used to control the alignment LED. When the switch is in the ON position, the alignment LED is activated and two low power (<5 mW) laser beams are emitted from the end of the sensing head. These beams indicate the positions where the DPV measurements are taken (position of the measurement volume). See section 2.1.1 The sensing head for more details.

▪Emergency stop (4) *CPS OPTION ONLY*

For DPV-0100 to DPV-0102, the emergency stop button is a laser safety feature only. Pushing on the emergency stop will immediately stop the laser source. Starting with DPV-0103, the emergency stop button will stop both the CPS laser (if option is purchased) and will interrupt any movement of the XY scanning unit.

Connections panel

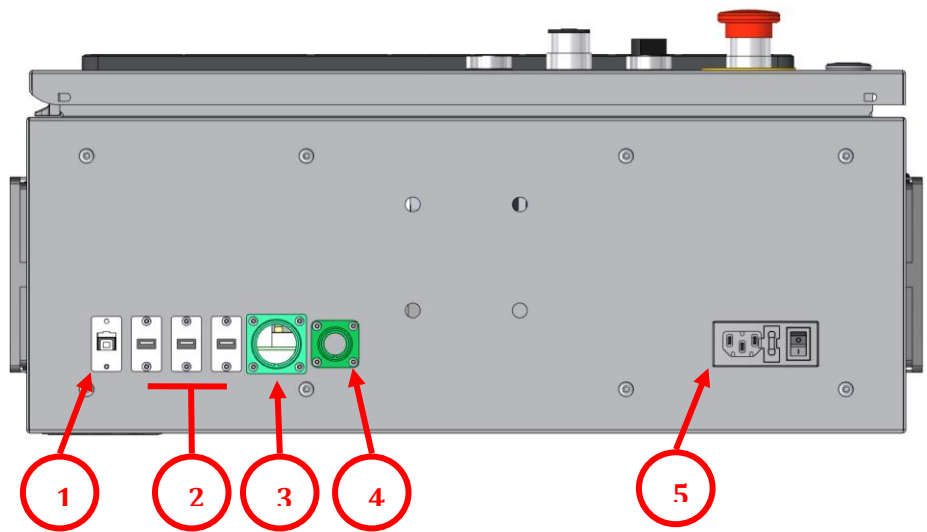


FIGURE 4 CONTROL MODULE CONNECTIONS PANEL

▪RJ45 Ethernet connector (1)

The RJ45 allows the user to connect the DPV Evolution to any network.

▪USB connectors (2)

The USB connectors allow the user to connect any USB peripherals to the DPV Evolution such as USB sticks, keyboard or mouse.

▪Scanning module connector (3)

The connector is used to connect the XY scanning module to the control module.

▪Interlock connector (4) *CPS OPTION ONLY*

The external interlock is a laser safety feature. This connector allows the user to remotely stop the laser source. It is the operator's responsibility to use the input to setup laser safety procedure at the location where the DPV Evolution will be used. See diagrams below for more details.

- Power connector (5) and main switch
120Vac 50/60Hz or 220Vac 50/60Hz. Must be configured at factory.

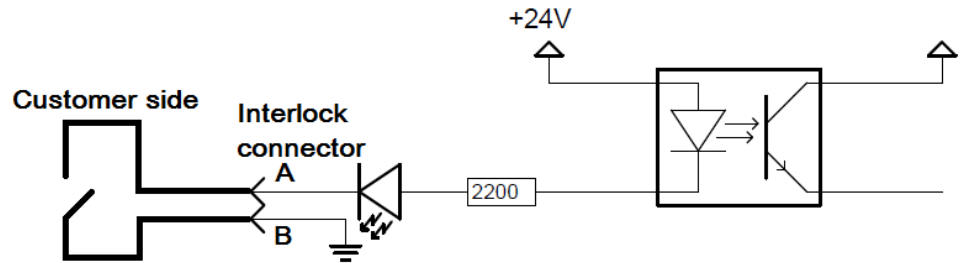


FIGURE 5 INTERLOCK CIRCUIT

2.1.4 THE CALIBRATION MODULE

This module contains a tungsten lamp used to calibrate the DPV Evolution for temperature measurements. The lamp itself has been calibrated prior to shipment using a high precision pyrometer (NIST traceable). The operator introduces the single end of the optical cable into the aperture on the front panel of the calibration module, and then follows the procedure described in section 5.2. *Temperature calibration*. Current LED displays allows for precise adjustment of the lamp temperature.

2.1.5 PLUMESPECTOR (OPTION)

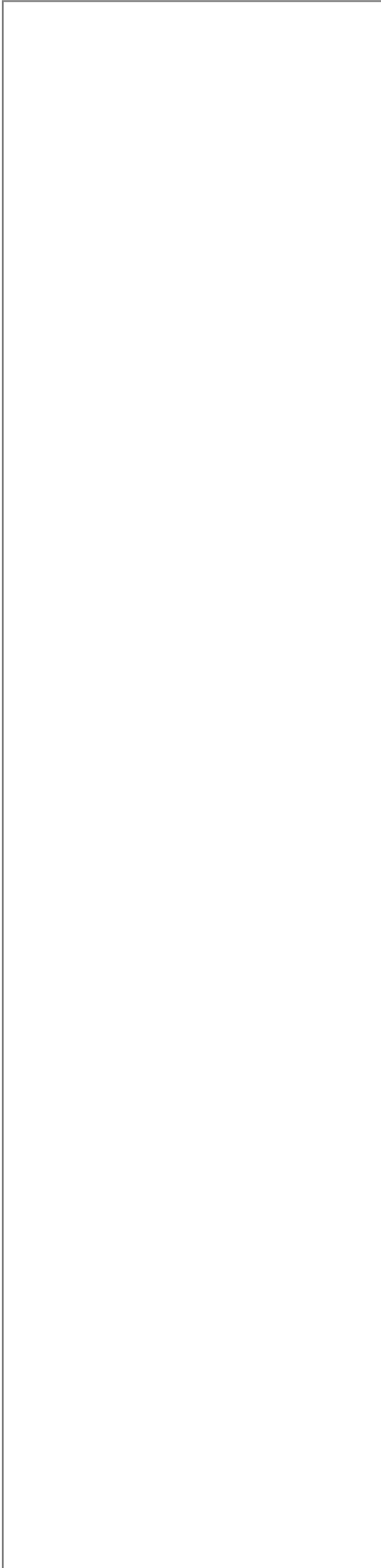
As an option, the DPV could include the **PlumeSpector** capabilities. This option uses a 2D CCD camera. It comes with a special head that could be installed 90 degrees to the spray plume and 200mm away from gun axis. It provides live video streams of the process as well as measurement of spray plume's WIDTH, POSITION, HEIGHT and INTENSITY.

Calculation principles

The following explains the basic principles used by the DPV Evolution to provide temperature, diameter & velocity measurements.

Velocity is obtained by dividing the distance between the image of the two slits in the measurement volume (real distance between the slits on the photomask multiplied by the magnification factor of the lens) by the "time of flight" between the two peaks of the particle signal (illustrated in Figure 2 Two-Slits mask), as estimated by the computer through waveform analysis. Velocity is the most precise of the DPV Evolution's measurements limited only by the frequency drift of the scope card's crystal oscillator. Re-








calibration is therefore not necessary.

Temperature measurement is based on two-wavelength pyrometry theory. Temperature is directly proportional to the ratio Signal detector #1 / Signal detector #2, assuming that heated particles are gray body emitters and emissivity is constant for all particles for a given spraying condition. For a given temperature, size & shape changes the amplitude of a particle's signal. Assuming spherical particles, the amplitude varies proportionally to the square of the particle's diameter. However, because signal filtering occurs in the detection electronics, a better estimate of the diameter is obtained from the time integral of the complete signal normalized for (i.e. multiplied by) velocity.

2.2 TECHNICAL DATA

<p>System including</p> <ul style="list-style-type: none"> - DPV eVOLUTION controller - DPV eVOLUTION scanning unit - DPV eVOLUTION calibration unit - DPV eVOLUTION optical sensor and cable (10m) - Lens holder - Power cables - Scanning unit cables (10m) - Reusable carrying case - Photomasks - Spare windows 	<p>Carrying case dimensions Length 95 cm Width 95 cm Height 98 cm</p>																				
<p>DVP eVOLUTION control module</p> <p>Dimensions</p> <p>Width 580 mm</p> <p>Height 770 mm</p> <p>Length 305 mm</p>	 <p>FIGURE 6 CONTROL MODULE</p>																				
<p>Calibration module</p> <p>Dimensions</p> <p>Width 304 mm</p> <p>Height 200 mm</p> <p>Length 340 mm</p>	 <p>FIGURE 7 CALIBRATION MODULE</p>																				
<p>Scanning module</p> <p>Dimensions</p> <p>Width 152 m,</p> <p>Height 367 mm</p> <p>Length 706 mm</p>	 <p>FIGURE 8 SCANNING MODULE</p>																				
<p>Measurement ranges</p> <p>Temperature: We list here some typical values (minimum measurable temperatures);</p> <table border="1" data-bbox="565 1705 1302 1843"> <thead> <tr> <th></th> <th colspan="2">Plasma configuration</th> <th colspan="2">Non-plasma configuration</th> </tr> <tr> <th>Emissivity</th> <th>0.4</th> <th>0.8</th> <th>0.4</th> <th>0.8</th> </tr> </thead> <tbody> <tr> <td>dia=20µm</td> <td>1650 °C</td> <td>1550 °C</td> <td>1300 °C</td> <td>1150 °C</td> </tr> <tr> <td>dia=20µm</td> <td>1350 °C</td> <td>1250 °C</td> <td><1050 °C</td> <td><1050 °C</td> </tr> </tbody> </table> <p>Velocity: 5 to 1200 m/s depending on photomask used Diameter: 10 to 300µm depending on photomask used</p>			Plasma configuration		Non-plasma configuration		Emissivity	0.4	0.8	0.4	0.8	dia=20µm	1650 °C	1550 °C	1300 °C	1150 °C	dia=20µm	1350 °C	1250 °C	<1050 °C	<1050 °C
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dia=20µm	1350 °C	1250 °C	<1050 °C	<1050 °C																	

3. INSTALLATION & SET-UP

Step 1. Mount sensor head (1) on the scanning unit. The sensor head can be set on either side of the spray plume between the spray gun (2) and the work piece (3).

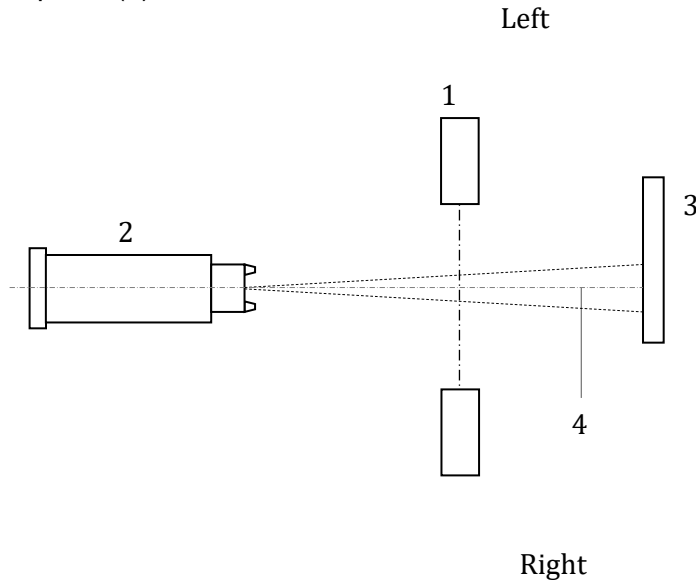


FIGURE 9 DPV EVOLUTION INSTALLATION DRAWING ORIENTATION


Step 2. Connect the scanning unit to the control module.

Step 3. Switch on controller main switch.

Step 4. Acknowledge Windows user password window by pressing the [ENTER] key. Windows boots and the desktop will be displayed.

Enter password if required.

Step 5. Start DPV Evolution software by double-clicking the corresponding icon on the desktop. After system communication check out is completed, the graphical user interface (see section 5.3 DPV Evolution software) will be displayed.

Step 6. Calibrate the scanning unit by pressing the “Center Slide”  icon on the home page of the software. Once the calibration is completed the unit will stay calibrated until the software is shut down.

Do not attempt to calibrate the scanning unit if the spray torch is active.

Dry & clean air must always be fed to the air purge connector at 1.7-2.7 bar (25-40 PSI)

Step 7. Position sensor head 100 mm (8) from the plume axis (4).

Step 8. Position sensor head in such a way that it never aims directly into the plasma flame itself (5), otherwise the measurements will reflect the plasma temperature instead of the particle’s temperature.

WARNING
CAUTION

It is not necessary to take the reference measurements at the exact same stand-off you use for coating, as long as you keep the reference distance (6) constant over time. See Figure 11 DPV Evolution installation drawing.

Step 9. If monitoring is required while spraying, set measuring point within measuring area (7), away from the substrate because of flow perturbation phenomena as the spray hits the substrate.

Step 10. Turn the alignment switch and position the 2 red dots perpendicular to the plume direction, in the middle of the plume.

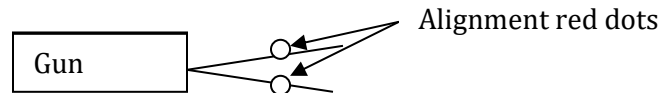



FIGURE 10 DPV EVOLUTION INSTALLATION DRAWING RED DOT POSITIONNING

Step 11. Load the appropriate (if already developed) setup file by clicking on the folder icon and choose *load setup* option.

Step 12. Start the spray torch.

Step 13. Once everything is stable (plasma, flame, powder injection, etc...) Press the “Auto center”  icon. The DPV will scan the plume and find its center.

Step 14. The DPV is now ready.

See section 6.4 for parameters optimization

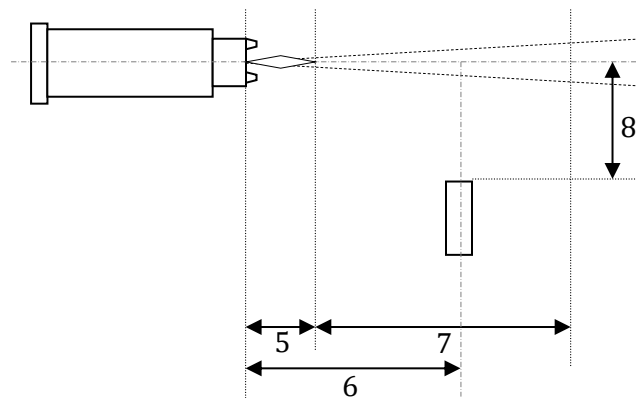


FIGURE 11 DPV EVOLUTION INSTALLATION DRAWING

4. MAINTENANCE

4.1 HOW TO CHANGE PHOTOMASK

Depending on the velocity & diameter ranges you expect for a given process, you could have to choose another photomask. The DPV-eVOLUTION is delivered with 2 photomasks, one for velocities below 400 m/s, and the other one for velocities 400 m/s and higher. The different masks are:

Below 400 m/s

Mask P4590170 (30201-00806-00)

400 m/s and higher

Mask HV105110180(30201-00807-00)

Mask G2 for coldspray meter system (30201-00805-00)

Should you have to change the photomask, proceed as follows:

Step 1. Remove the set screw that holds the lens with the optical cable. NEVER REMOVE OR UNTIGHTEN THE SET SCREW THAT HOLDS THE BLOCKING RING ON THE OPTICAL CABLE; IF YOU DO SO, IT WILL CHANGE YOUR VELOCITY CALIBRATION. CALL TECNAR.

Step 2. Gently remove the optical cable termination out of the lens.

Step 3. Gently remove the two screws that hold the photomask in place on the optical cable; BE CAREFUL NOT TO LOSE THEM !!!

Step 4. Carefully remove the photomask from the optical cable.

Step 5. Insert the new photomask making sure that the slot on the photomask is aligned with the slot on the fiber cable's termination. Gently tighten the two screws.

Step 6. Insert the optical cable back into the lens making sure the slot is upward, and then gently tighten the set screw.

Step 7. In the Home screen in the DPV software, click on the wrench button at the top right of the velocity histogram. Select the proper photomask in the dropdown menu.

Step 8. Remember that if you change the photomask, generally it is because you expect a different speed range for the particles, so do not forget to adjust the speed acceptance range in the Detection Tuning Screen, otherwise you could have the impression that the system does not detect any particle.

Step 9. Place the mask you removed in the photomask box in order to protect it from dirt & shock.

4.2 WHEN AND HOW TO CHANGE THE PROTECTIVE WINDOW

In order to prevent the expensive relay lens from any damage, a disposable protective window is installed between the spray plume and the lens. The window should be replaced when non-removable (either by air or lens paper) deposits or scratches are observed.

Use a spanner wrench to remove the blocking ring at the front end of the lens. Carefully remove the dirty window and replace it by a clean one. **DOING SO, BE CAREFULL NOT TO PUT ANY GREASE ON THE NEW WINDOW.** Insert and gently tighten the blocking ring.

Note that DPV Evolution is delivered with one protective window installed, and two (2) spare ones. If you run out of disposable windows, **CONTACT TECNAR** (we always keep them in stock).

4.3 TEMPERATURE CALIBRATION

In order to obtain the best performances from your DPV it is recommended to check calibration of your unit on a regular basis. To do so:

Step 1. Install the Plasma photomask, P4590170 (30201-00806-00), by following procedure 5.1. ***Calibration can only be achieved with the Plasma type mask.***

Step 2. Remove the DPV sensor from the scanning unit support and insert it in the calibration unit (1). The key way has to be aligned on the top with the screw. You should feel the sensor touch the end of the calibration port when it's properly inserted. Once the lens is properly inserted, lock it in place using the setscrew on top of the calibration port, making sure that the screw is aligned with the key way.

WARNING
CAUTION

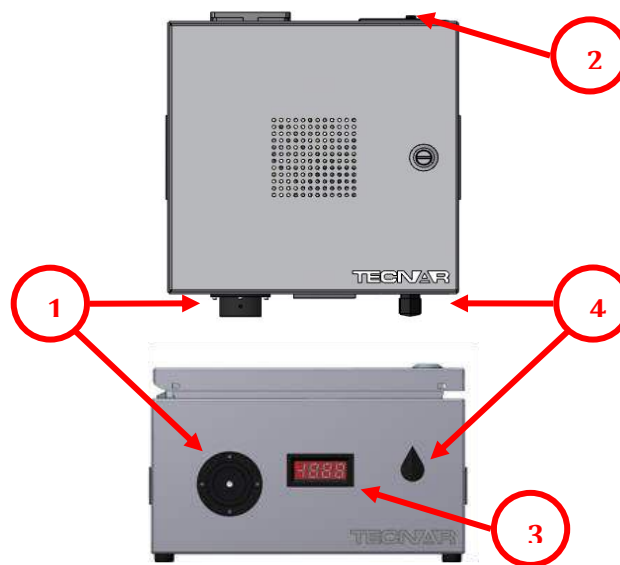

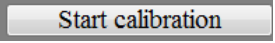










FIGURE 12 CALIBRATION UNIT CONTROLS

Step 3. Connect the calibration power inlet (2) to a wall socket. Turn the unit ON. *The calibration unit accepts voltage from 115 to 250Vac.*

Step 4. Start the DPV Evolution software and go to the calibration tab using the  button at the bottom of the screen.

Step 5. On the calibration unit, turn the control knob completely counter clockwise (4). The current display (3) should read 0.

Step 6. On the DPV Evolution click on the  icon to begin the calibration process.


Calibration Lamp					Measured values			
Temperature	Current	D1	D2	D1/D2	Temperature	dT	Arm	Lock
1840	4.86	0.38	0.753	0.5054				
2061	5.63	0.794	1.343	0.5912				
2282	6.47	1.479	2.183	0.6775				
2503	7.44	2.578	3.376	0.7637				

Step 7. Do not turn ON the lamp until the message on screen disappears.

Step 8. Start the first point by clicking on the Arm icon on the first row (1).

Step 9. On the calibration unit turn the control knob clockwise to the first position (around 4.86 A). Wait five seconds for the measured temperature to stabilize. Once the measurements is stable press on the lock box.

Step 10. Repeat Step 7 and Step 9 for the next three points adjusting the control knob on the calibration unit accordingly.

Step 11. Once the calibration is completed, save it using the  button.

5. OPERATION

Here is a list of precautions concerning the use of the DPV-eVOLUTION unit & its related modules:

To avoid dirt penetration, the main cabinet doors should be kept always closed except for punctual access to the DVD-RW or for hardware verification as per TECNAR instructions.

When the optical cable must be manipulated & rolled up, the main precaution is to avoid small radius of curvature (keep radius of curvature above 15 cm) and brutal shape changes. When rolled-up on top of the cabinet, optical cable should in some way be attached (clamped) to the cabinet's roof. The lens should be covered with a plastic bag to avoid potential deposits.

Never hold the lens by the optical cable.

Make sure that the lens temperature is maintained below 75°C. To do so, apply proper air cooling. At all times, avoid drastic temperature change.

Keep the alignment LED OFF when you do not use it.

If your DPV-eVOLUTION was delivered with a power transformer, always use this particular transformer with the system. Do not use this transformer for any other equipment of yours.

If you must carry the DPV-eVOLUTION from your facilities to any other facility and that the unit is exposed to temperatures below 10°C during transportation, let it come back to room temperature (At least 6 hours) before turning it ON, otherwise condensation could occur on the different optical components.

When you move the sensing head with the XY scanning unit (in manual mode, or during an automatic scan), MAKE SURE THAT THE LENS AS NO CHANCE TO ENTER THE SPRAY PLUME ITSELF!!!

5.1 TURNING-ON THE DPV-2000

Turn-on the DPV-2000 at least 30 minutes before starting the experiment in order to allow the acquisition boards, the photodetectors and all the electronic to stabilize. **In fact, it is a good habit to keep the DPV-2000 ON all the time unless you won't use it for a long period (2 days or more).**

5.2 TEMPERATURE CALIBRATION

Your DPV-2000 is equipped with an easy-to-use temperature calibration module. It is a good habit to verify temperature calibration before starting a measurement campaign. To do so, follow instructions in 5.3.

CAUTION

WARNING

CAUTION

5.3 DPV EVOLUTION SOFTWARE

The DPV Evolution software is divided into 5 main tabs. Navigating between the tabs is accomplished by clicking on the icons at the bottom of the software window. The software is designed to be used with a mouse or a touch screen monitor. The different functions of the tabs are explained in detail below.

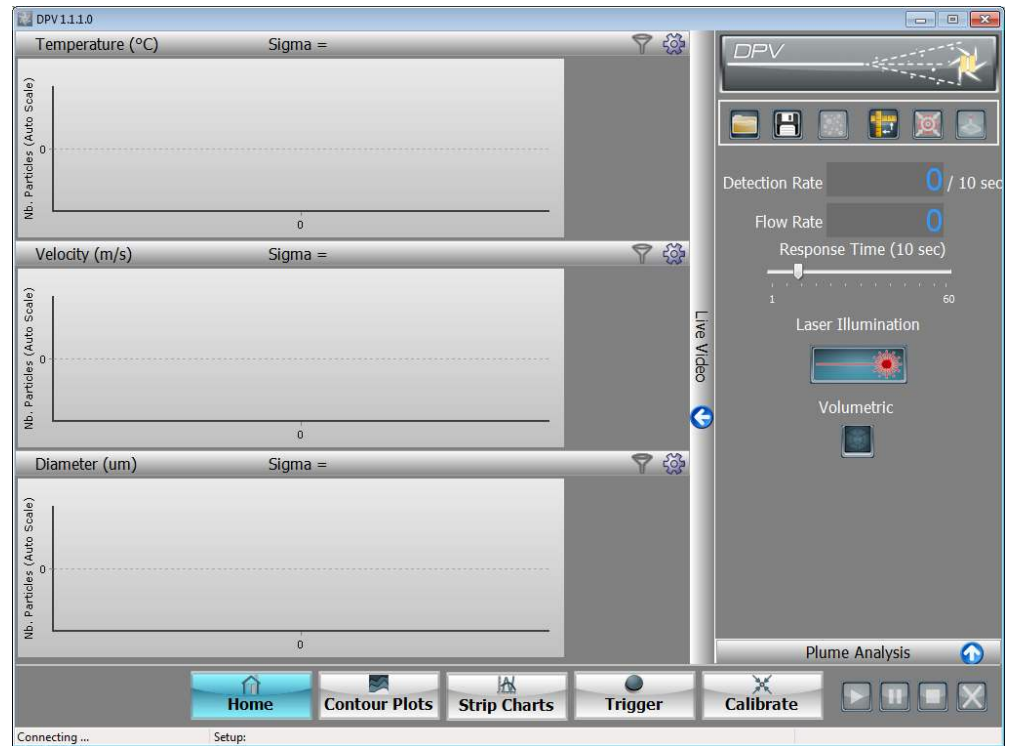


FIGURE 13 DPV EVOLUTION SOFTWARE

5.3.1 HOME TAB

This section explains in detail the operation of the DPV Evolution software Home tab.

5.3.1.1 HISTOGRAM

There are three histograms on the home tab. From those, the user can monitor the particles distribution analyzed by the DPV during a given amount of time (user adjustable). Three histograms (1) are available providing temperature, velocity and diameter statistics. The different components of the histograms are explained below. Note that on the right-hand side of each histogram, the mean value of the distribution is displayed. On top of each histogram the standard deviation is displayed. The vertical axis represents the population (number of particles) for each class (histogram bar). By default, the vertical axis of the histogram is automatically scaled to fit the entire window, and the **Normalized** label is

displayed on the vertical axis.

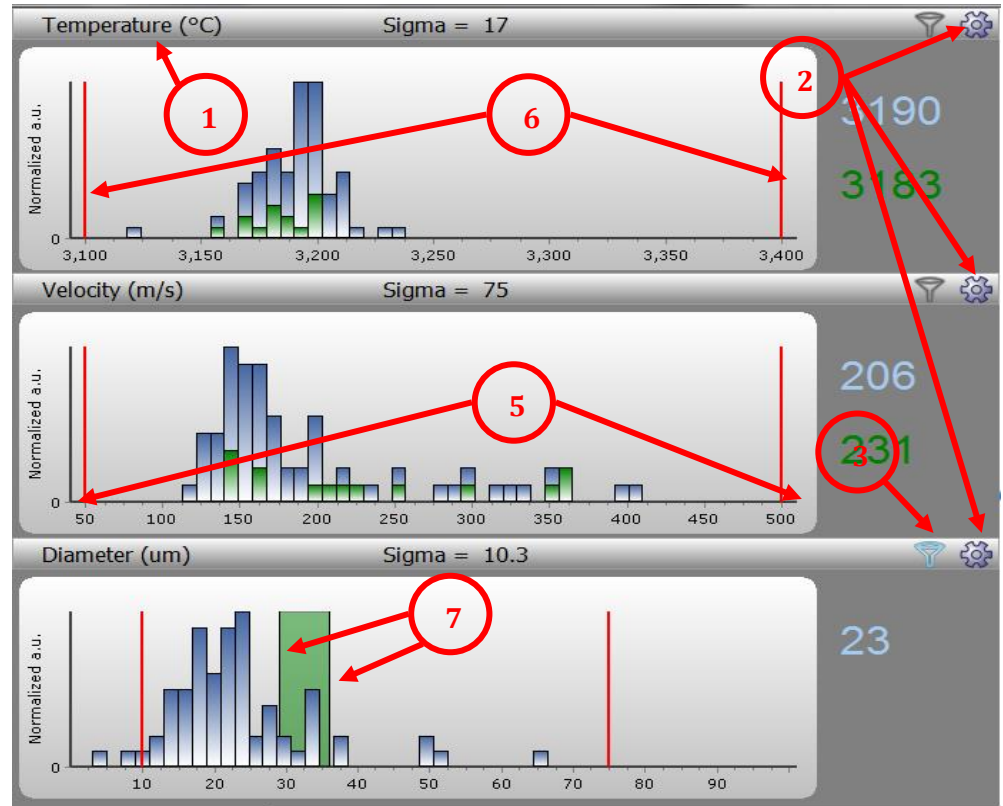


FIGURE 14 VELOCITY HISTOGRAM SETTINGS

One can configure the display and the option by clicking on the Histogram settings (2) icon. Use this icon to access the histogram settings menu.

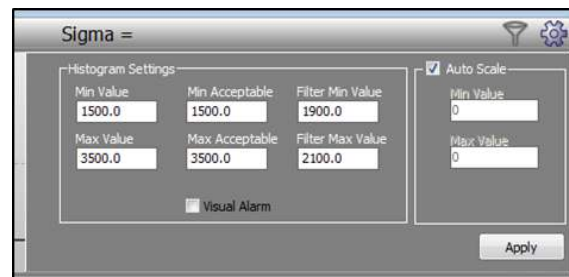


FIGURE 15 HISTOGRAM SETTINGS

5.3.1.2 GENERAL ADJUSTMENT FOR HISTOGRAM:

- Min Max Values

The x-axis (horizontal) (5) can be adjusted using [Value] fields. Adjusting this parameter will affect the display range on the horizontal axis.

- Min Max acceptable values

The red lines (6) show the [Acceptable] values for each of the measurements. When the mean value of a measurement is outside the

Acceptable range, the corresponding histogram section turns red.

- Filtered Min Max values

Filters can be applied to study a small population of particles. When a filter is activated on a particular histogram (3) a green rectangle will appear in the background indicating the range covered by the filter. On the other histograms, the particles that fall within the range of the filter will appear as green columns. The range of the filter (7) can be adjusted using the [Filter Value] fields.

5.3.1.3 PARTICULAR ADJUSTMENT FOR HISTOGRAM

- Velocity histogram settings

Mask width should be adjusted depending on the velocity & diameter ranges you expect for a given process. The DPV-eVOLUTION is delivered with 2 photomasks, one for velocities below 400 m/s, and the other one for velocities 400 m/s and higher. See section 4.1 *How to change photomask* section for more details on how to change the photomask. When you are in the Velocity histogram setting, simply select the appropriate photomask from the dropdown menu.

- Diameter histogram settings

For the DPV Evolution to provide accurate measurements of particles diameter, the particle’s average diameter (typically you should use the D-50 as supplied by the powder manufacturer) must be entered in the software. The following steps must be used to calibrate diameter for a given material:

1. Start the spray process & wait until powder injection is stable
2. Run an auto-centering so to find center of the spray plume
3. Enter the particles nominal diameter in the field [Target Diameter] then click the calibrate button.
4. Click Apply Changes so that the new calibration becomes active

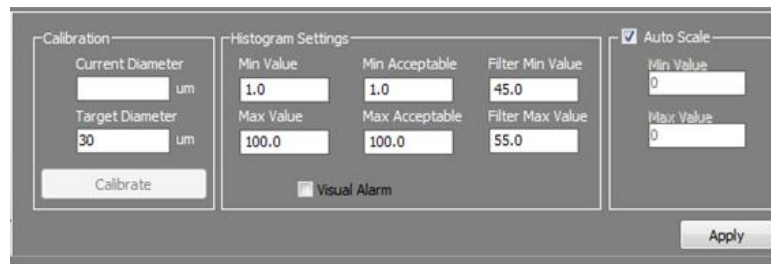


FIGURE 16 DIAMETER HISTOGRAM SETTINGS

5.3.1.4 HOME TAB - RIGHT PANEL

Here is a description of the right panel of the Home tab.

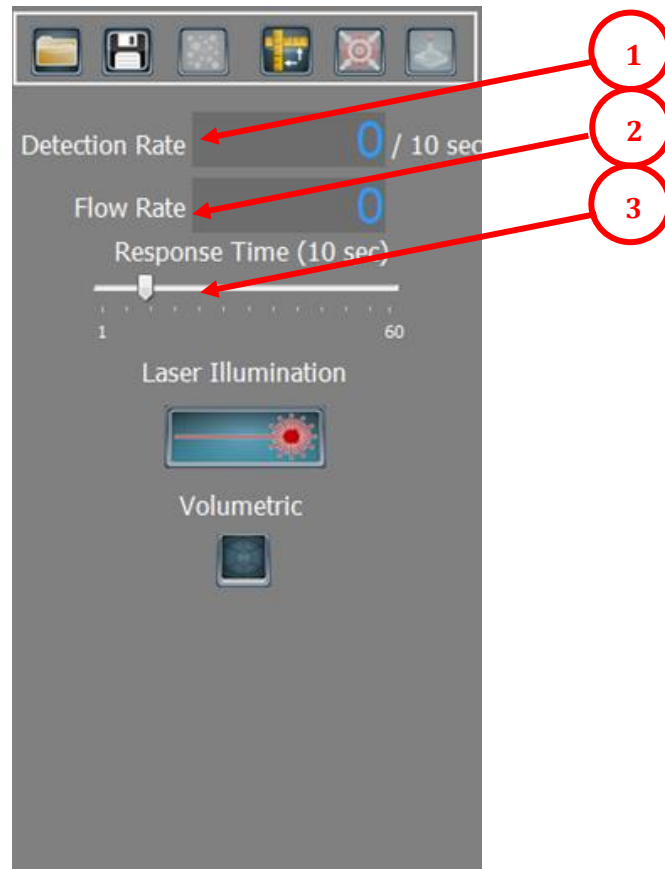








FIGURE 17 HOME TAB LEFT PANEL

Saved experiments and setups can be reloaded/replayed using the  icon.

Experiments and setups can be saved using the  icon.

The DPV Evolution software can record a pre-specified number of particles using the  icon. Before the recording starts, the user is prompted by the software to choose how many particles should be recorded.

It is necessary to calibrate the scanning unit before it can be used. Click the  icon to calibrate the unit. The calibration will be valid until the software is closed. Once calibrated the scanning module can be used to automatically scan the plume or manually move the sensor. Manual controls are accessed by clicking the  icon. Once the scanning unit is calibrated, you can hit the  [autocenter] button so to find center of the plume (point of maximum mass flow rate).

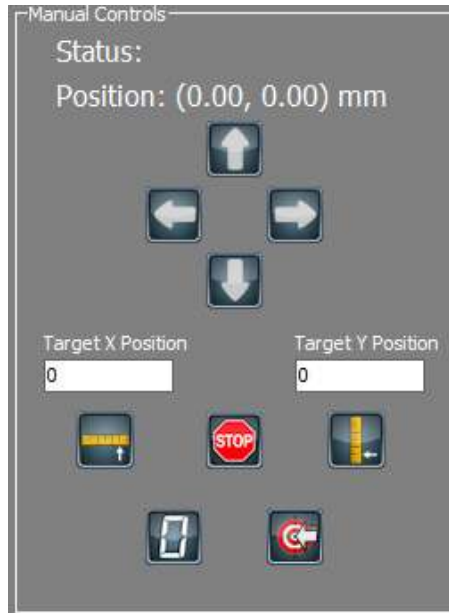






FIGURE 18 SCANNING UNIT MANUAL CONTROLS

The scanner can be moved manually using the arrows or sent to a particular position using the [Target Position] field and clicking the icon  or  to initiate the movement.

If you press the stop button the scanner will stop moving.

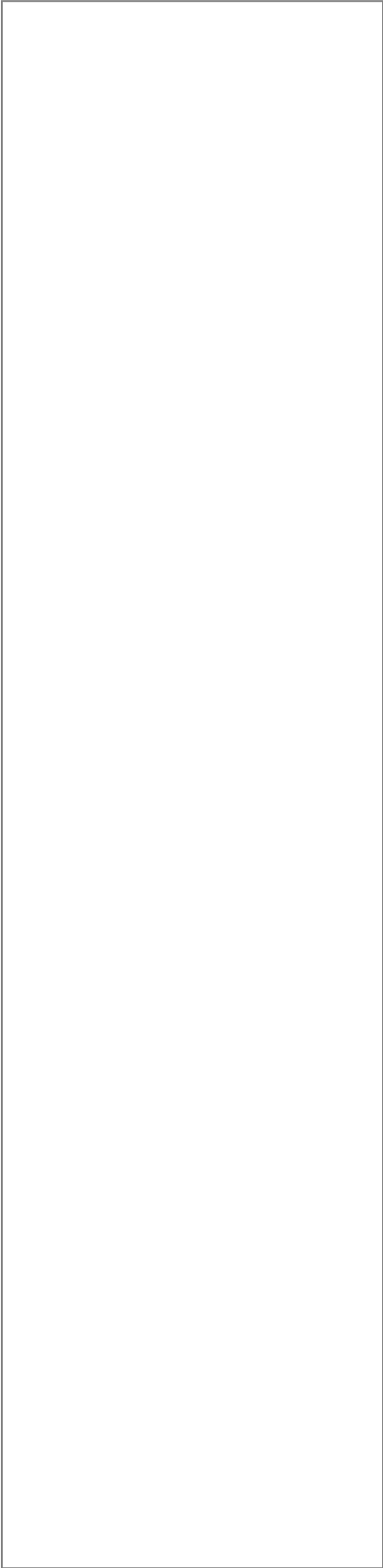
By pressing the zero button  you will reset to 0,0 your actual position. This gives you a new relative reference.

If you move your scanner and you want to return to the last autocenter position you can press on this button .

The DETECTION RATE [1] displayed corresponds to the effective performance of the system, that is how many GOOD particles were detected and analyzed per unit of time (a GOOD particle is one that successfully passed all the pattern recognition criteria).

The software also provides a measurement proportional to the number of particles passing by the measurement volume per unit time; this number is called FLOW RATE, and it is displayed in the left panel of the screen [2]. Knowing the size distribution of the sprayed material and the size of the measurement volume, the FLOW RATE can be related to mass flow or density of particles.

The RESPONSE TIME [3] slider is used to set the period over which the rolling average is calculated. For example, if RESPONSE TIME is set to 5 sec, it will take 5 sec before a change in the input parameters is fully reflected in the particle measurements.







By default, the DPV software displays frequency-type histograms, but the user can as well generate volumetric-type histograms by clicking the VOLUMETRIC button on the screen. The major difference between the two types of histograms is that volumetric ones consider the size of the particle. This means that a 30 μ m particle would contribute 27 times more to the histogram than a 10 μ m particle.

Finally, the laser Illumination button must be clicked when you are looking at cold particles. In such case you will lose the temperature measurement since monochromatic IR laser light is shined into the measurement volume. Be sure to click that button and to activate the laser prior to take cold particles measurements.

5.3.1.5 HOME TAB - ACQUISITION CONTROL SECTION



FIGURE 19 ACQUISITION CONTROL BUTTONS

-  The [pause] button is used to pause the acquisition or the playback of a recorded experiment
-  The [play] button is used to resume the acquisition or resume playback of a recorded experiment
-  The [stop] button is used to stop recording an experiment
-  The [close] button is used to stop playing a recorded experiment and return to live mode

5.3.2 CONTOUR PLOTS

Thanks to the XY scanning unit, cross sectional mapping of the spray plume is possible. Results of the scans can be plotted under the form of contour plots has shown on Figure 20 Contour plots.

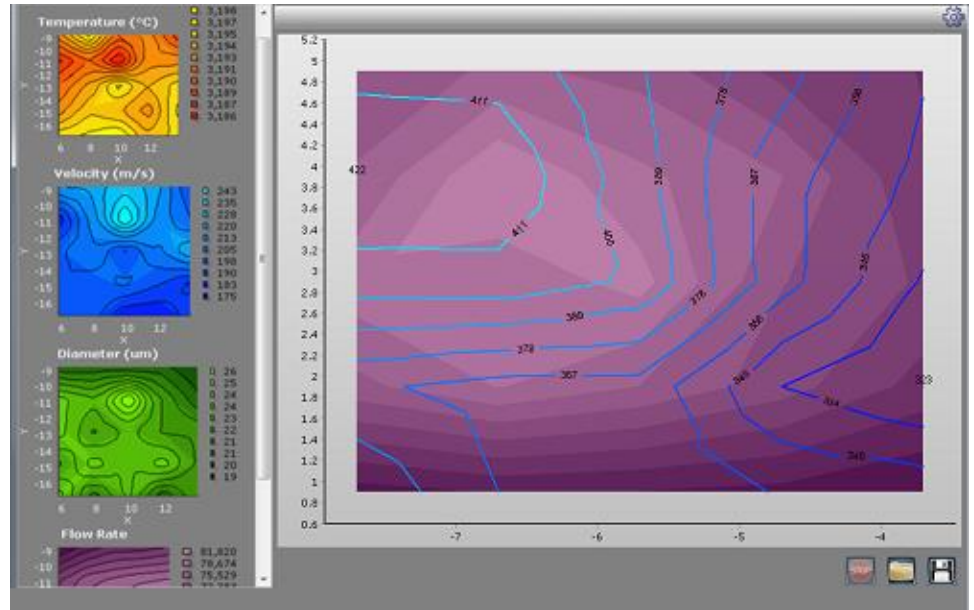


FIGURE 20 CONTOUR PLOTS

The first step to achieve a contour plot is to determine you grid of scan. To set the grid you need to press the setting icon at the top right of the screen. The following window will appear.

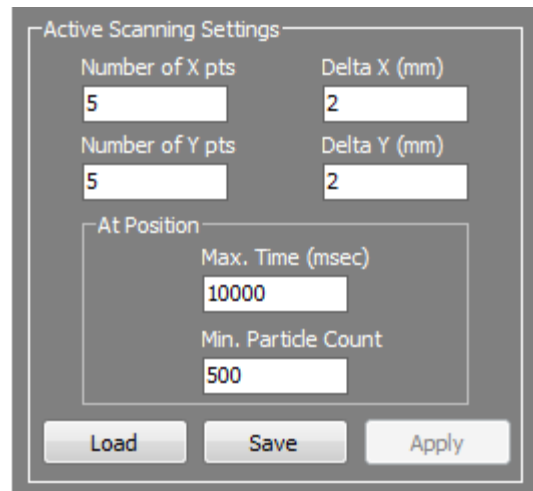


FIGURE 21 CONTOUR PLOTS ACTIVE SCANNING SETTINGS

In that window, you need to set the number of points per axis you want and the distance between two points. The center of your grid is the current

position of the scanner. The second step is to determine the number of good particles acquired per point. 500 particles usually give a good statistical analysis. If the scanning position is out of the spray of course the CSM will not be able to see particle. In such case you need to tell the software how long it must wait until the scanner moves to the next point. To change the time, you need to edit the field name Max. Time (msec).

You can save or load your settings by pressing the corresponding button in the active scanning settings window.

When you are ready to start your scan, you press the floppy icon at the right of the screen. You enter the name of the file you want to save, and the scan will automatically start after you press the save button.

You can stop a scan by pressing the stop button.

You can also recall a contour plot by pressing the folder icon. The recorded contour plot can be found in the folder statistics inside the root folder of the DPV.

5.3.3 STRIP CHARTS

Strip charts give you the average value over time of the measurements of the DPV.

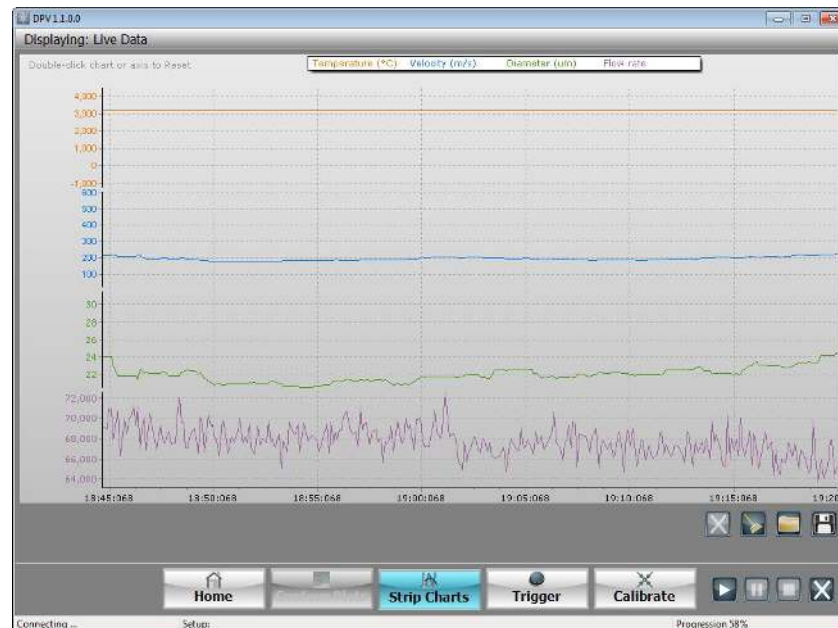
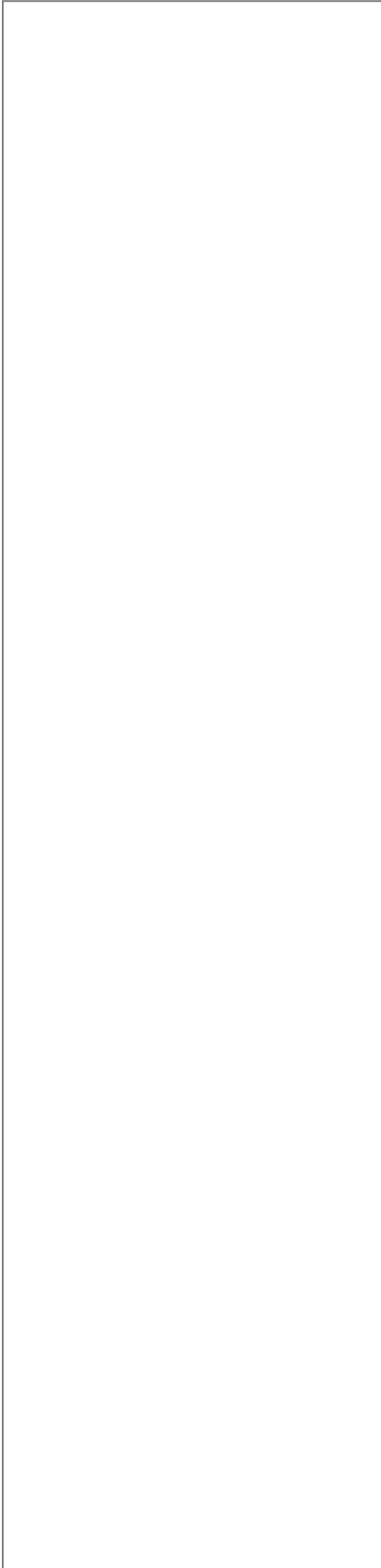






FIGURE 22 STRIP CHARTS



 This icon returns to live mode when you have loaded a previous run.

 This icon clears and resets the graphic.

 The folder icon recalls a previous run of strip charts

 The floppy disk icon saves the strip charts on screen in a CSV file.

You can zoom by dragging on the Y axis or the X axis

YOU CAN MOVE THE CHARTS BY DRAGGING IN THE GRAPHIC.

5.3.4 TRIGGER

This screen has been designed to help the operator with analysis adjustments. It basically transforms your screen into an oscilloscope. The operator can look at the different signals collected from the process and then adjust the input range, the trigger level, etc. that will best fit the ongoing spraying conditions. This screen has been also designed to allow for on-line adjustment of the particle's rejection criteria.

This screen is also very useful to detect abnormalities. For example, one can rapidly see if the noise level is of the same order of magnitude as it usually is. Also, one can easily verify the amplitudes of Signal A & B; they should always be about the same for given spraying conditions. Figure 23 Trigger screen is an example of the trigger screen.

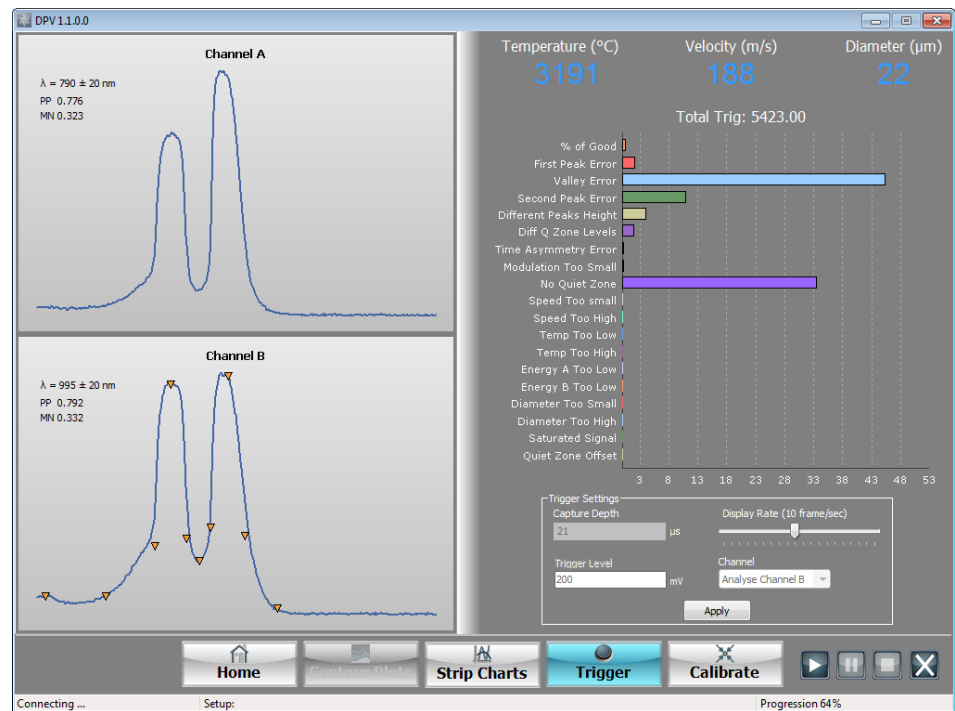
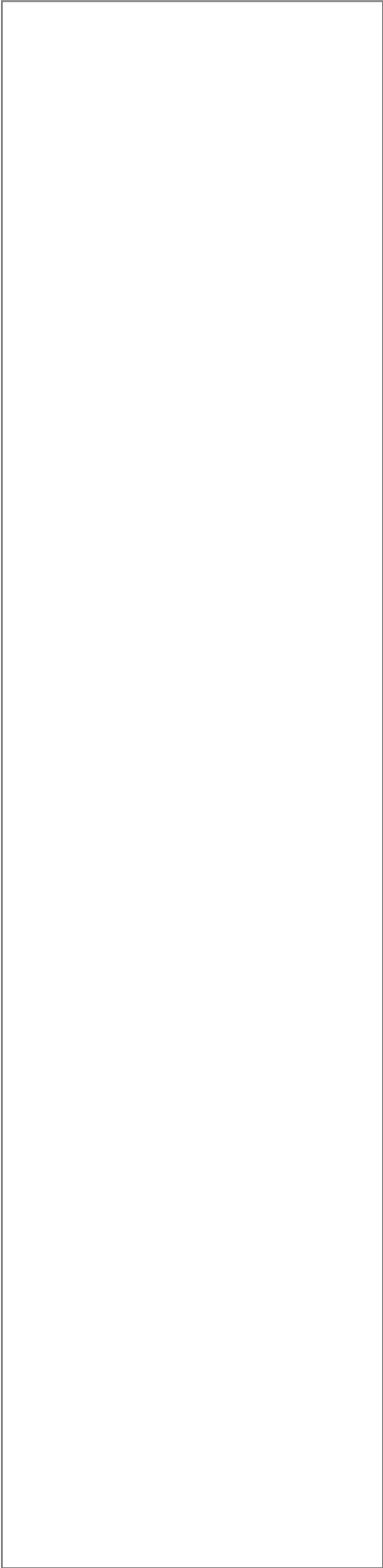


FIGURE 23 TRIGGER SCREEN

The two windows on the left of this screen display raw signals coming out of detector A & detector B respectively. In the top left corner of each window, three values are displayed: the wavelength band for each channel, the peak-peak amplitude (PP), which corresponds to the difference between the point of maximum and the point of minimum voltage within the acquisition window, and the Mean value (MN), which indicates the average level of the signal within the acquisition window. Signal analysis may be performed on either channel A or channel B by selecting the ANALYZE A or ANALYZE B options at the bottom right of the screen. In the case presented here, analysis is performed on channel B; you can notice the



presence of cursors identifying the peaks, the half-heights, the valley & the quiet zones (for matter of baseline establishment, the system will identify two relatively flat regions, one on each side of the signal; we refer to those regions as QUIET ZONES).

The top right part of the screen shows the means values measure by the DPV:

- Temperature
- Velocity
- Diameter

The Total Trig label shows the number of trigger events that took place during the integration period set in the Home tab.

The particles analyzed are categorized into 19 sub-categories:

- Good
- No First peak
- No valley
- No second peak
- Different peaks height
- Different quiet zone levels
- Time Asymmetry Error
- Insufficient Modulation
- Missing quiet Zone
- Low speed
- High speed
- Low temperature
- High temperature
- Low Energy on channel A
- Low Energy on channel B
- Low Diameter
- High Diameter
- Saturated
- Quiet zone offset

All those sub-categories are shown on Figure 24 Trigger screen- Analysis result section. The graphic shows the percentage of particles in each sub-

category.

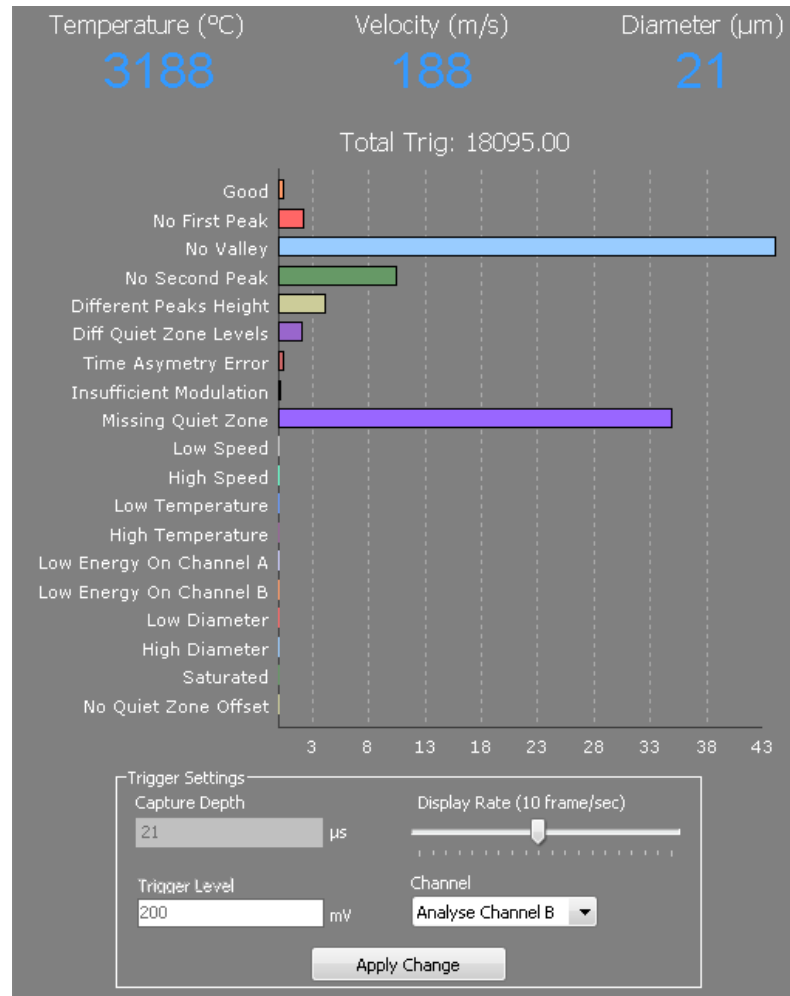


FIGURE 24 TRIGGER SCREEN- ANALYSIS RESULT SECTION


5.3.4.1 TRIGGER SETTINGS

Let’s now move to the bottom right part of the screen, which is used for optimization of the data acquisition. The operator can adjust CAPTURE DEPTH (the width of the acquisition window) depending on the duration of a typical event.

The last parameter is TRIGGER LEVEL. It must be treated with great care. Its value ranges from 0mV to 5000mV. The general idea is to set the TRIGGER LEVEL high enough to avoid triggering on noise or undesired signals (this will increase the detection performance of the system), but not so high that you miss a significant portion of the low energy particles (the small and/or cool ones).

See section 6.4 for parameters optimization

WARNING**5.4 PARAMETERS OPTIMIZATION FOR A TYPICAL EXPERIMENT**

First make sure that the X&Y slides are about in the middle of their travel; to do so, calibrate the scanning unit by pressing the “Center Slide”  icon on the home page of the software. Once the calibration is completed the unit will stay calibrated until the software is closed. Insert the sensing head into the sensing head holder of the XY Scanning Unit. Turn-on the ALIGNMENT button on the DPV-eVOLUTION; red light will then be injected backward in the optical fiber bundle. Use a piece of paper, hold it right in the axis of the torch and then manually move the hole Scanning unit box in the X direction until you obtain a relatively sharp (in focus) image of the two optical fibers on the paper in the middle of the plume position. Vertical rough alignment can be done by moving the torch until the mid-point between the two alignment fibers aims at the torch axis. AUTO-CENTERING routine will take care of the fine alignment.

One last detail to pay attention to: thermal spray plumes are rarely horizontal. This means that velocity measurements could be affected since they assume that particles are traveling perpendicular to the 2-slits photomask. Therefore, we recommend that you evaluate the angle of the thermal spray plume. Knowing this angle, you can compensate for it by giving a slight inclination to the sensing. Keep in mind that the velocity measurement will be affected as the COSINE of the angle. As you know, for angle 10 degrees and less, the COSINE is pretty much “1” so not much error introduced on the velocity.

Do not forget to release the ALIGNMENT button/key when the procedure is over.

Before starting the spray process, DO NOT FORGET TO CONNECT THE AIR-COOLING LINE to the sensing head holder; usually, 20 to 40 PSI airflow is sufficient to keep the lens clean & cool.

You are ready to start spraying and optimizing you parameters.


5.4.1 TRIGGERS SETTINGS

Get to the Trigger Screen and look at the particle signals. The first parameter to adjust is the TRIGGER LEVEL. Values range from 0mV to 5000mV. If you set the TRIGGER LEVEL too low, your particle counting rate will also be low because you will often trigger on noise, and consequently getting valuable statistical samples will take more time. On the other hand, if you set the TRIGGER LEVEL too high, your particle counting rate will also be very high because you start looking only at signals of large amplitude (this means that you are discriminating in favor of large particles). We found out that a TRIGGER LEVEL between 150 &

160 does not cause any size discrimination in the majority of the processes.

Adjust CAPTURE DEPTH in such a way that typical particle signal can be totally included within the acquisition window and that quiet zones can be correctly established on both side of the signal. BEWARE! If you set Capture Depth too low, you might lose the biggest, slowest particles.

5.4.2 FINAL CENTERING

To activate the fully automated computer controlled auto-centering routine, Press the “Auto center”  icon. The DPV will scan the plume and find its center (in terms of mass flow).

CAUTION

NOTE THAT POWDER INJECTION TAKES A CERTAIN TIME TO REACH DYNAMIC EQUILIBRIUM DEPENDING ON THE SETUP YOU USE. IT IS THEREFORE STRONGLY RECOMMENDED TO WAIT FOR A STABLE PLUME BEFORE STARTING THE AUTO-CENTERING ROUTINE. A message will appear on the screen to indicate that centering is finished

5.4.3 ADJUSTING REJECTION CRITERIA

Valid particles are identified according to specific criteria that may be adjusted in the Trigger Screen. The DPV software analyses each acquisition. First the DPV software tries to do pattern recognition, if some test failed the particle is rejected. After that, the DPV software checks if the particle met the rejection criteria. If any of the rejection criteria is met, the particle is rejected and categorized into one of the 18 sub-categories. To adjust the rejection criteria or to see the particles rejected you simply click on the graphic bar for which you want to obtain details in the trigger screen. All the parameters are described in the sub-section below. Note that when you click on a parameter what you see on the oscilloscope section are only the particles referring to that parameter. By example, if you click on the GOOD horizontal bar you see on the oscilloscope section only the good particles; in that case those particles are used to calculate DPV measurements.

5.4.3.1 GOOD

The sub-category “GOOD” shows the particles that are considered for the calculations (Velocity, temperature and diameter). The graphic shows the percentage of the good particles relative to the total number of triggers received. No specific action can be achieved in that sub-category.

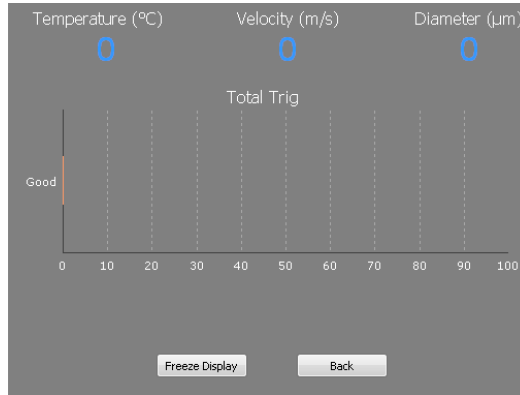


FIGURE 25 TRIGGER SCREEN- GOOD PARTICULES SECTION

5.4.3.2 NO FIRST PEAK

The sub-category “NO FIRST PEAK” shows the particles rejected because they show characteristics that are not within the acceptable range. The graphic shows the percentage of rejected particles showing no first peak during the acquisition. No specific action can be achieved in that sub-category.

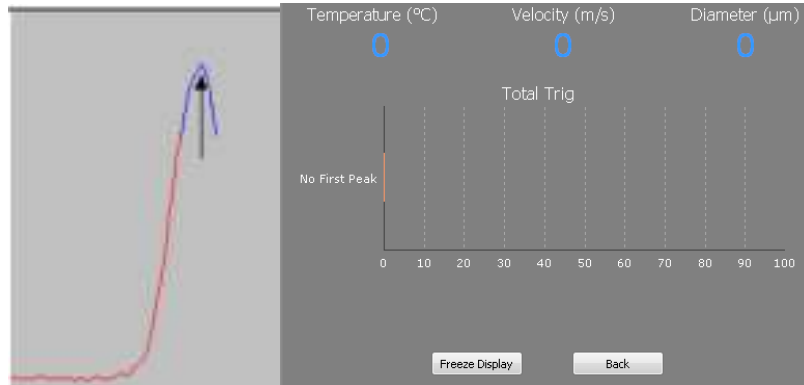
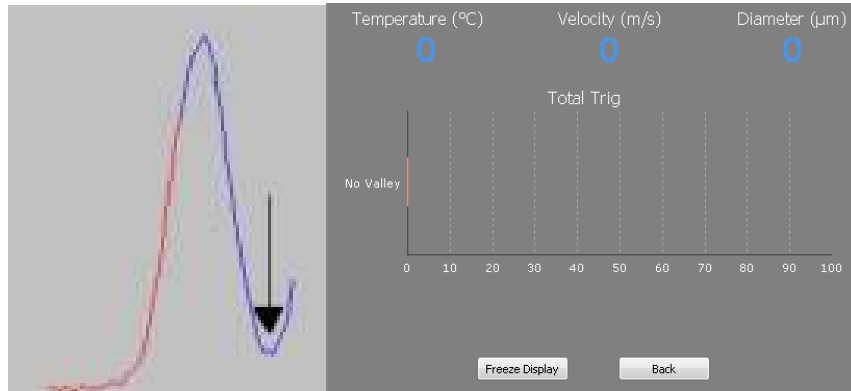


FIGURE 26 TRIGGER SCREEN- NO FIRST PEAK

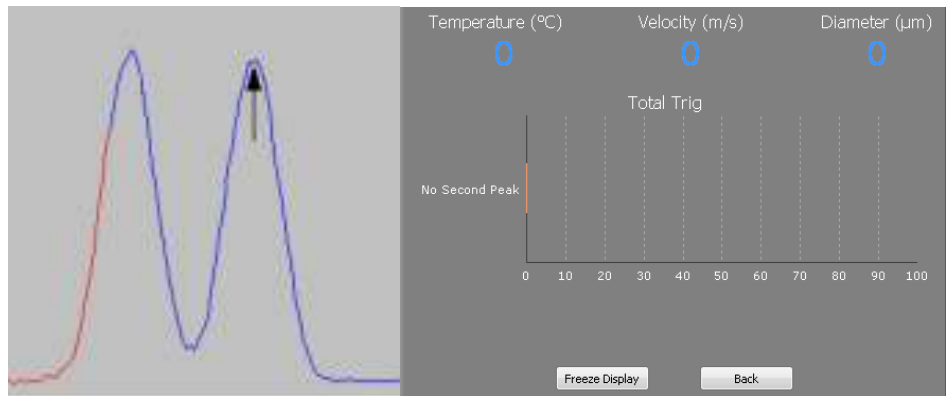
5.4.3.3 NO VALLEY

The sub-category “NO VALLEY” shows the particles rejected because they show characteristics that are not within the acceptable range. The graphic shows the percentage of rejected particles showing no valley during the acquisition. No specific action can be achieved in that sub-category.



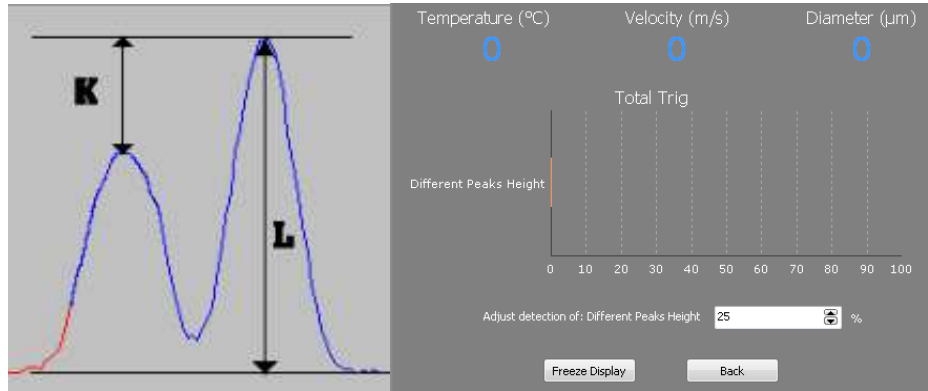
5.4.3.4 NO SECOND PEAK

The sub-category “NO SECOND PEAK” shows the particles rejected because they show characteristics that are not within the acceptable range. The graphic shows the percentage of rejected particles showing no second peak during the acquisition. One possible cause to obtain only 1 peak if an incorrect orientation of the sensor head/photomask assembly (a 90 degrees error would translate into seeing only 1 peak).



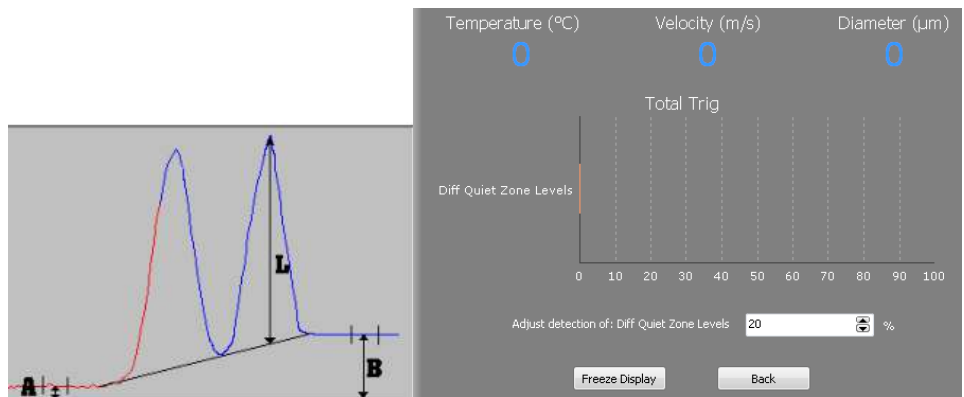
5.4.3.5 DIFFERENT PEAKS HEIGHT

The sub-category “DIFFERENT PEAKS HEIGHT” shows the particles rejected because they show characteristics that are not within the acceptable range. The graphic shows the percentage of rejected particles showing different peak heights during the acquisition. You can modify the acceptable criteria by changing the percentage of different between the 2 peaks height. K/L must be smaller than the percentage chosen in the “DIFFERENT PEAKS HEIGHT” panel. 25% covers the majority of the processes.



5.4.3.6 DIFFERENT QUIET ZONE LEVELS

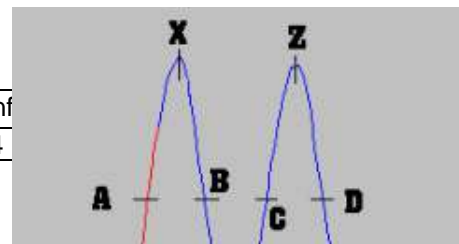
The sub-category “DIFFERENT QUIET ZONE LEVELS” shows the particles rejected because they show characteristics that are not within the acceptable range. The graphic shows the percentage of rejected particles showing different quiet zone levels during the acquisition. You can modify the acceptable criteria by changing the percentage of difference between the 2 peaks height. $|B-A|/L$ must be smaller than the percentage chosen in the “DIFFERENT QUIET ZONE LEVEL” panel. 20% covers the majority of the processes.



5.4.3.7 TIME ASYMMETRY ERROR

The sub-category “TIME ASYMMETRY ERROR” shows the particles rejected because they show characteristics that are not within the acceptable range. A time asymmetry error can arise from 2 particles of similar size, out of focus and slightly shifted in time. Each particle will show a peak on the oscilloscope and since they are slightly shifted in time it will look like 2 peaks on the screen. The way to validate that this is not a real particle is by looking at the symmetry of the peak in time.

Here are the 4 equations used to verify this criterion (time position is used in the equations):

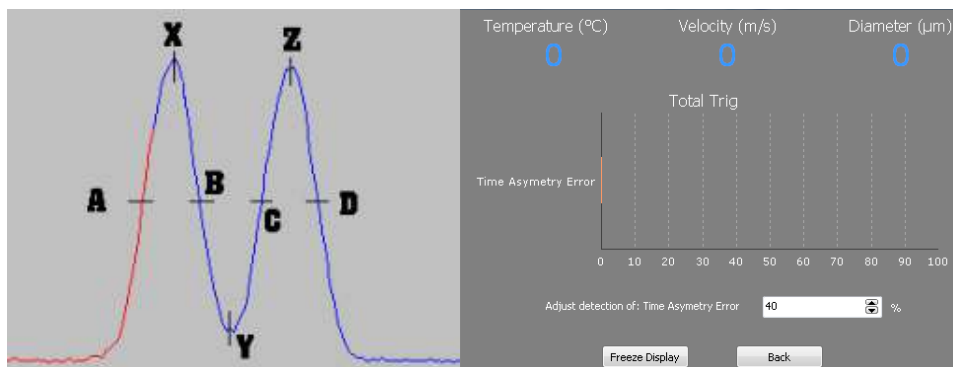


- $\frac{||X-Y|-|Z-Y||}{|X-Y|} < J$
- $\frac{||X-Y|-|Z-Y||}{|Z-Y|} < J$
- $\frac{||A-B|-|C-D||}{|A-B|} < J$
- $\frac{||A-B|-|C-D||}{|C-D|} < J$

Where J is the Maximum time asymmetry.

When J is higher than the percentage written in the “TIME ASYMMETRY ERROR” section, the particle is rejected.

The graphic shows the percentage of rejected particles showing time asymmetry error during the acquisition. You can modify the acceptable criteria by changing the percentage of J. J must be smaller than the percentage chosen in the “TIME ASYMMETRY ERROR” panel. 40% covers the majority of the processes.

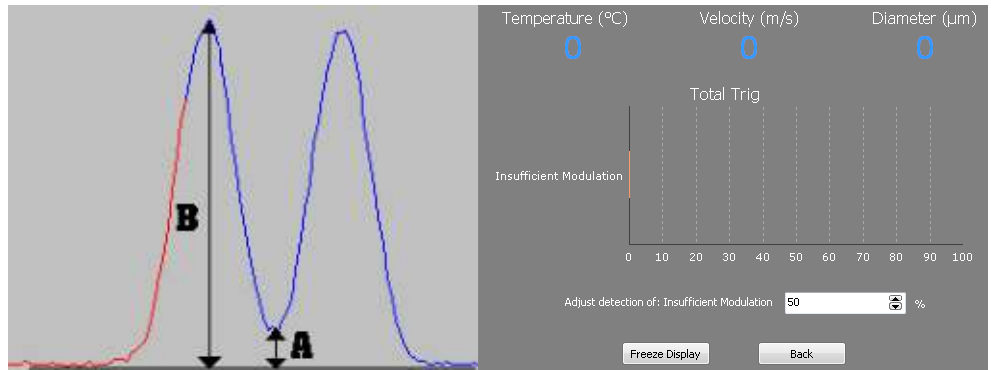


5.4.3.8 INSUFFICIENT MODULATION

The sub-category “INSUFFICIENT MODULATION” shows the particles rejected because they show characteristics that are not within the acceptable range. An insufficient modulation particle rejection occurs when the particle is not at the focal point. In such case the valley will not return near the noise level. You can modify the acceptable criteria by changing the percentage of minimum acceptable modulation. $1 - \frac{A}{B} \geq$

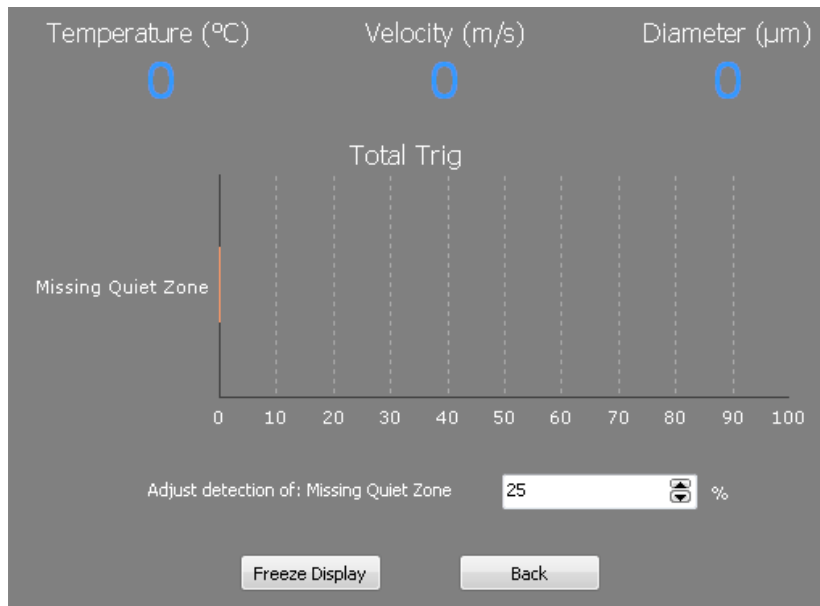
Minimum acceptable modulation

50% covers the majority of the processes.



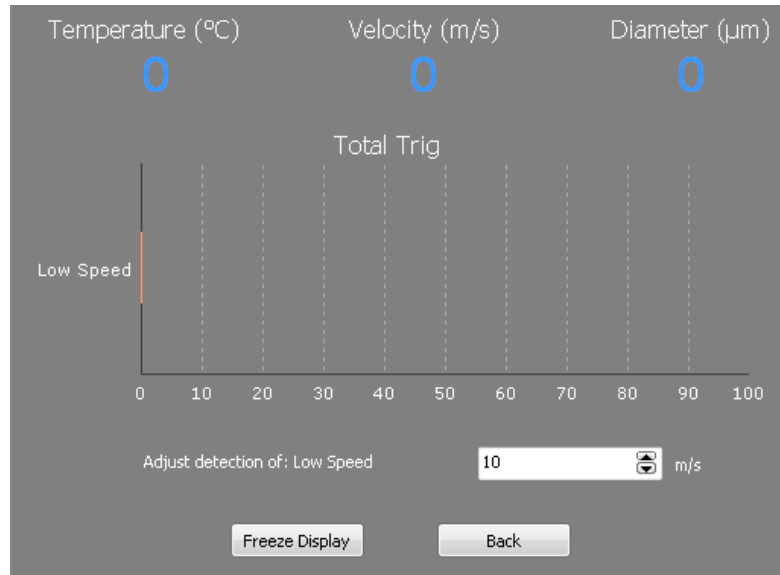
5.4.3.9 MISSING QUIET ZONE

The sub-category “MISSING QUIET ZONE” shows the particles rejected because they show characteristics that are not within the acceptable range. A Missing quiet zone particle rejection occurs when you can observe signal in the noise zone. The DPV software computes the mean voltage in the noise zone. If the peak value in the noise zone is higher than X% of the mean value, the particle (buffer) is rejected. Another reason to explain Missing Quiet Zones is a Capture Depth that is set too narrow. You can modify the acceptable criteria by changing the percentage of Missing quiet zone. 25% covers the majority of the processes.



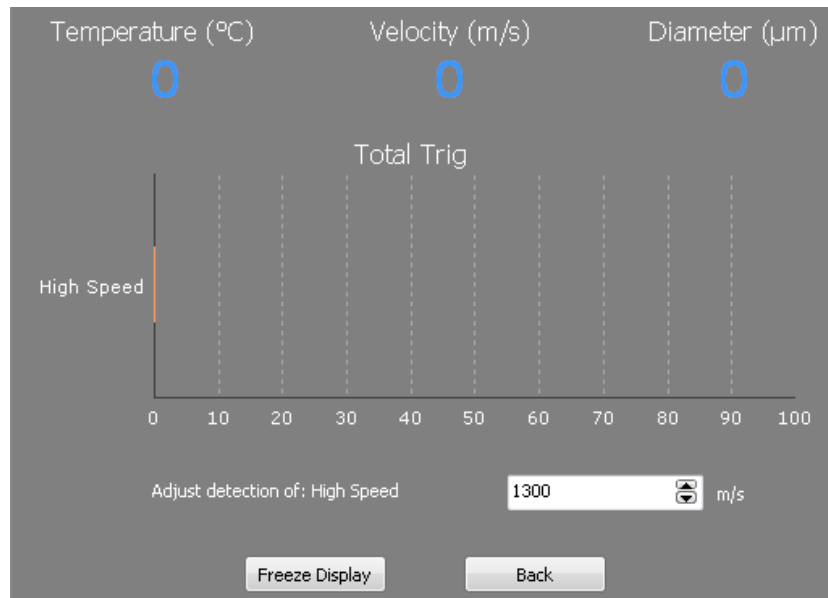
5.4.3.10 LOW SPEED

The sub-category “LOW SPEED” shows the particles rejected because they show characteristics that are not within the acceptable range. A low-speed particle rejection occurs when the particle speed is lower than the value entered in that setting. You can modify the acceptable criteria by changing the limit of low speed. 10m/s is the default value.



5.4.3.11 HIGH SPEED

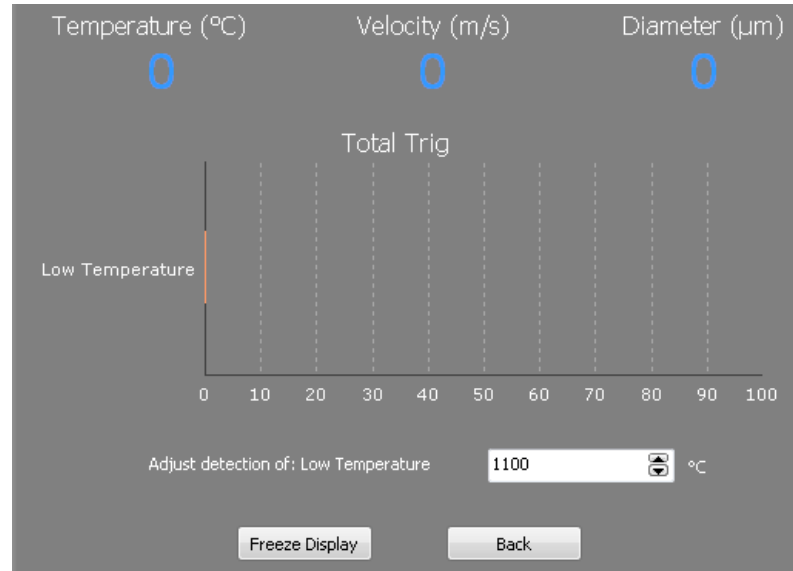
The sub-category “HIGH SPEED” shows the particles rejected because they show characteristics that are not within the acceptable range. A high-speed particle rejection occurs when the particle speed is higher than the value entered in that setting. You can modify the acceptable criteria by changing the limit of high speed. 1300m/s is the default value.



5.4.3.12 LOW TEMPERATURE

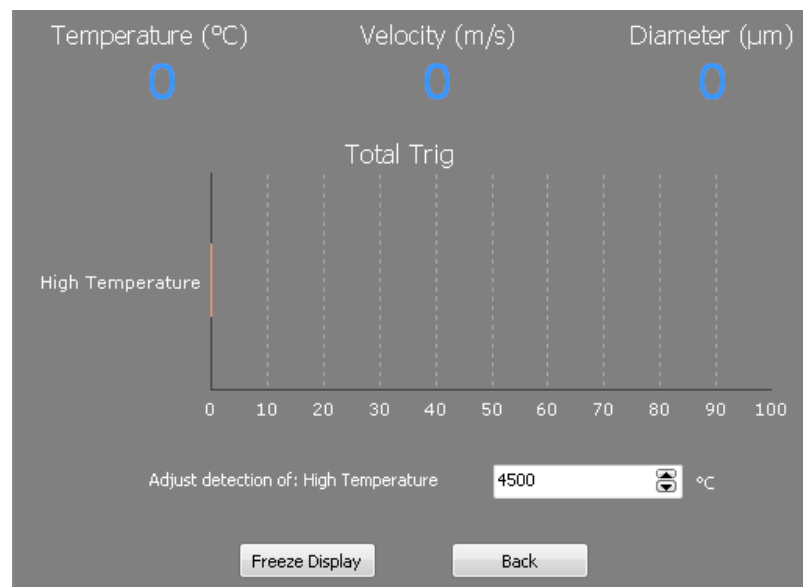
The sub-category “LOW TEMPERATURE” shows the particles rejected because they show characteristics that are not within the acceptable range. A low temperature particle rejection occurs when the particle temperature is lower than the value entered in that setting. You can modify the acceptable

criteria by changing limit of low temperature. 1100°C is the default value.



5.4.3.13 HIGH TEMPERATURE

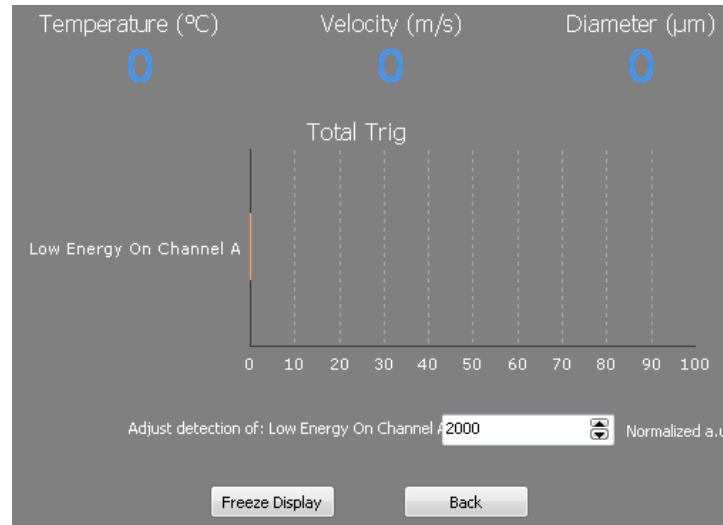
The sub-category “HIGH TEMPERATURE” shows the particles rejected because they show characteristics that are not within the acceptable range. A High temperature particle rejection occurs when the particle temperature is higher than the value entered in that setting. You can modify the acceptable criteria by changing the limit of high temperature. 4500°C is the default value.



5.4.3.14 LOW ENERGY ON CHANNEL A

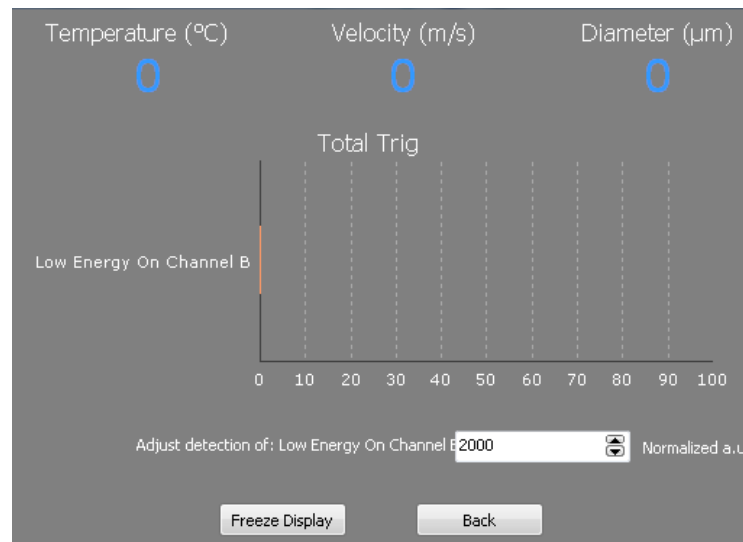
The sub-category “LOW ENERGY ON CHANNEL A” shows the particles rejected because they show characteristics that are not within the

acceptable range. A LOW ENERGY ON CHANNEL A particle rejection occurs when the particle energy is lower than the value entered in that setting. Basically, it means that there is not enough signal. You can modify the acceptable criteria by changing the limit of low energy on channel A. 2000 is the default value.



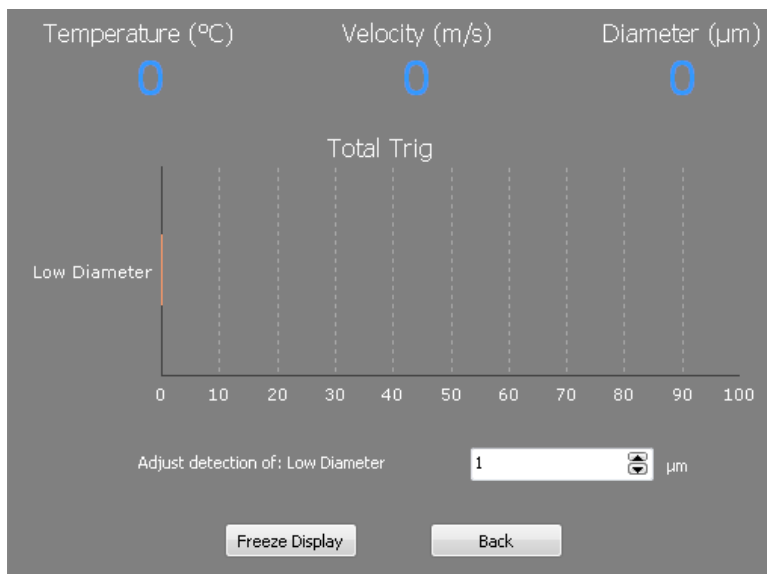
5.4.3.15 LOW ENERGY ON CHANNEL B

The sub-category “LOW ENERGY ON CHANNEL B” shows the particles rejected because they show characteristics that are not within the acceptable range. A LOW ENERGY ON CHANNEL B particle rejection occurs when the particle energy is lower than the value entered in that setting. Basically, it means that there is not enough signal. You can modify the acceptable criteria by changing the limit of low energy on channel B. 2000 is the default value.



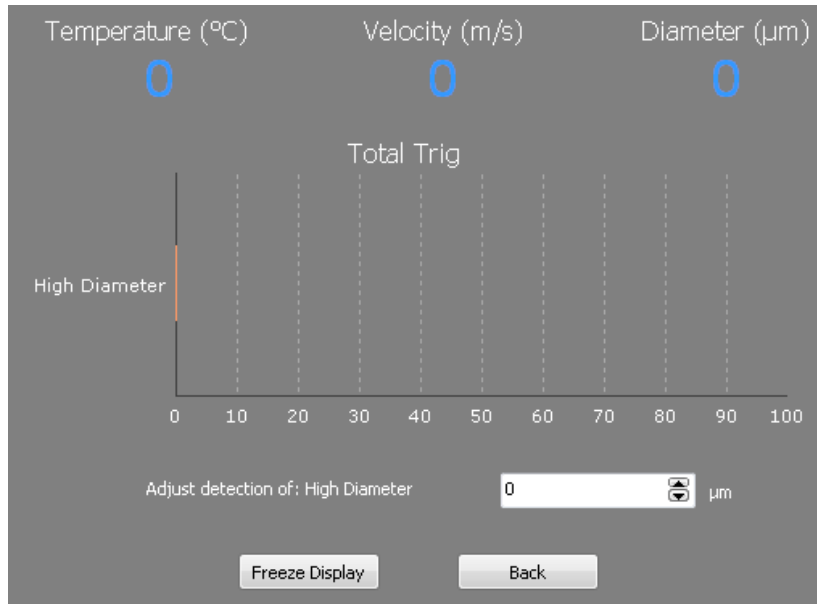
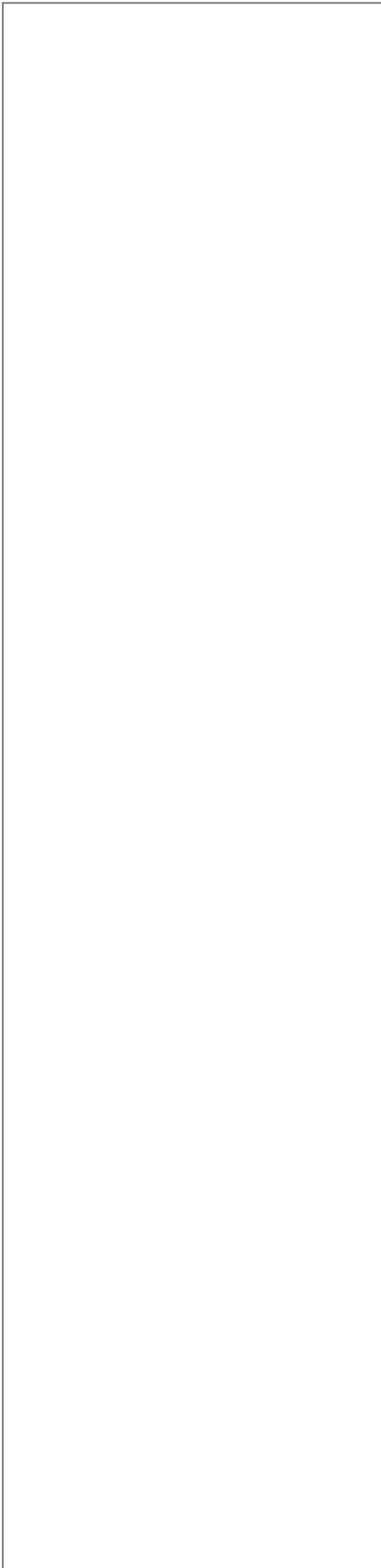
5.4.3.16 LOW DIAMETER

The sub-category “LOW DIAMETER” shows the particles rejected because they show characteristics that are not within the acceptable range. A low diameter particle rejection occurs when the particle diameter is lower than the value entered in that setting. You can modify the acceptable criteria by changing the limit of low diameter. 1um is the default value.



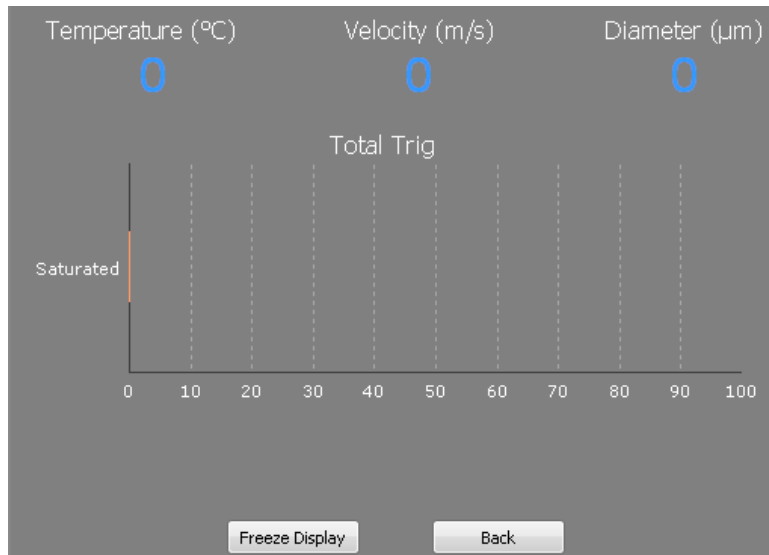
5.4.3.17 HIGH DIAMETER

The sub-category “HIGH DIAMETER” shows the particles rejected because they show characteristics that are not within the acceptable range. A high diameter particle rejection occurs when the particle diameter is higher than the value entered in that setting. You can modify the acceptable criteria by changing the limit of high diameter. 500um is the default value.



5.4.3.18 SATURATED

The sub-category “SATURATED” shows the particles rejected because they show characteristics that are not within the acceptable range. A saturated particle rejection occurs when the particle signal saturates the acquisition card. You cannot modify this setting.



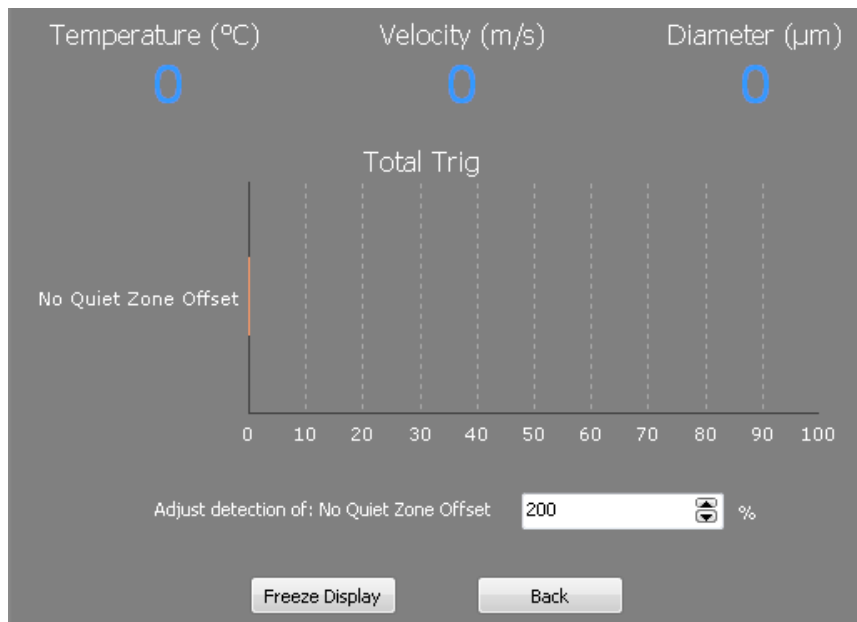
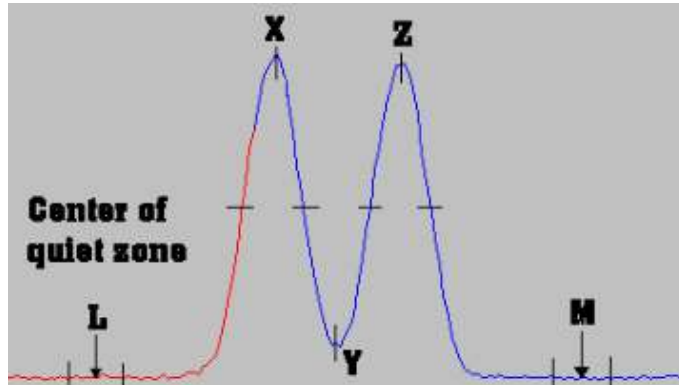
5.4.3.19 QUIET ZONE OFFSET

The sub-category “QUIET ZONE OFFSET” is used to set the position where to analyze the noise section (L and M). The quiet zone location will be

$$L = X - 200\% | X - Y |.$$

$$M = Z + 200\% | Z - Y |$$

The number entered as to be higher than 100%

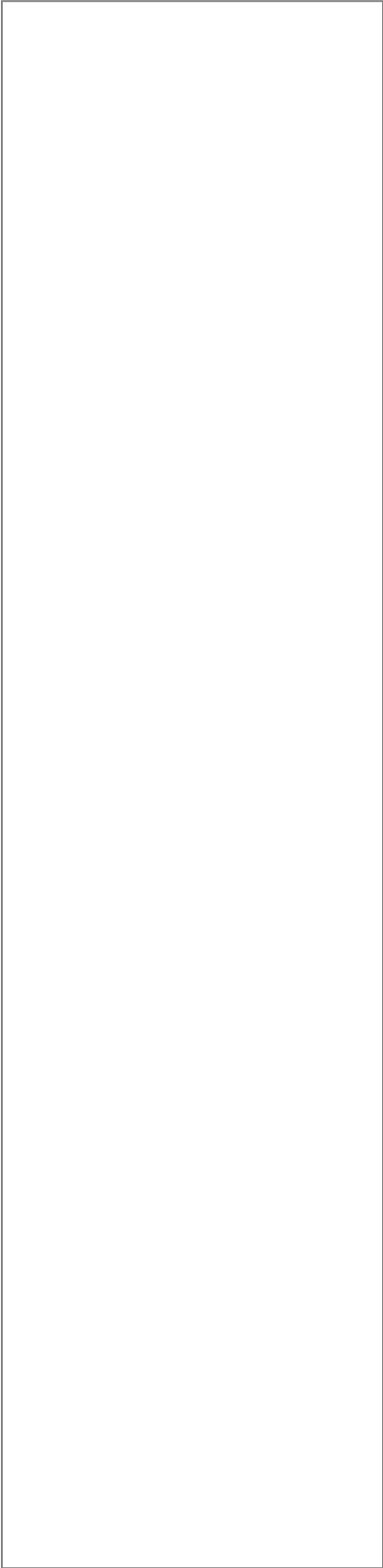


NOTE THAT adjustments will probably be different for different materials or different thermal spray processes. It is therefore a good idea to create a library of setup files.

Depending on the spray process/powder/gun you are looking at, different parameters will have to be adjusted, such as DIAMETER COEFFICIENT, MASK WIDTH, Display scales, temperature calibration, etc.

When you feel your set of parameters is pretty much optimal for a given process/powder, you SAVE a setup file in the home tab.

Then, when coming back to this process in the future, all you will have to



do is LOAD the corresponding setup file and your system will be configured exactly the same way it was before.

PLEASE NOTE THAT YOUR DPV IS DELIVERED WITH A SET OF PATTERN RECOGNITION PARAMETERS THAT HAS BEEN FOUND APPROPRIATE FOR THE MAJORITY OF THE SPRAY PROCESS/CONDITIONS TYPICALLY ENCOUNTERED IN THERMLA SPRAY.

6. ABOUT CALCULATION OF TEMPERATURE, VELOCITY & DIAMETER USING THE DPV-EVOLUTION

The objective of the present section is to establish some definitions as well as to explain in greater detail the basic principles behind measurement of temperature, velocity & size as performed by the DPV-2000.

6.1 DEFINITIONS & HYPOTHESIS

TOF \equiv Time of Flight of the particle between the two slits

V_p \equiv velocity of the particle

s \equiv center to center distance between the slits

A_a \equiv Area under the two peaks curve of channel a (corresponds to λ_1)

A_b \equiv Area under the two peaks curve of channel b (corresponds to λ_2)

Energy \equiv Time integral of the two peaks curve normalized by velocity & corrected for difference in peak heights. Values are logged to *.PRT files under

Columns "ENERGYA" and "ENERGYB"

$E(\lambda_1)$ \equiv Theoretical energy that particle irradiates at λ_1

$E'(\lambda_1)$ \equiv Energy measured at λ_1 , and corrected for peak height

difference (equivalent to ENERGY A as logged to the .PRT file)

$E(\lambda_2)$ \equiv Theoretical energy that particle irradiates at λ_2

$E'(\lambda_2)$ \equiv Energy measured at λ_2 , and corrected for peak height

difference (equivalent to ENERGY B as logged to the .PRT file)

$\varepsilon(\lambda_1)$ \equiv emissivity of the particle at λ_1

$\varepsilon(\lambda_2)$ \equiv emissivity of the particle at λ_2

$T(K)$ \equiv Temperature of the particle in Kelvins

d \equiv diameter of the particle

$K \equiv$ grouped constants considering optical properties of the system

$K_2 \equiv$ constant

$K_3 \equiv$ constant

$R \equiv E(\lambda_1) / E(\lambda_2)$

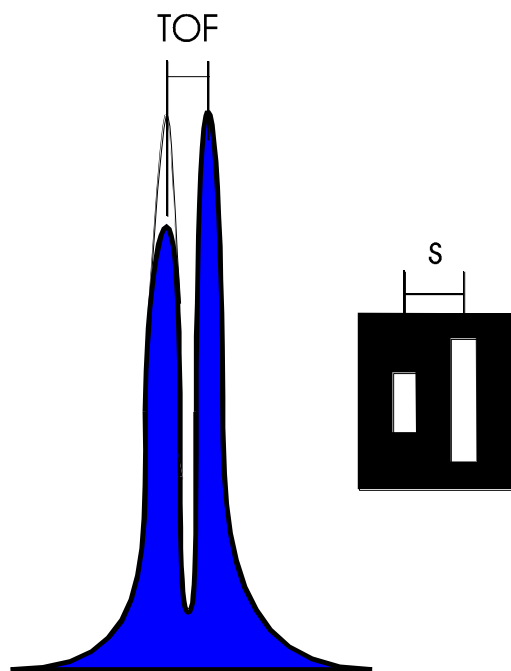
Hyp1:Melted particles are gray body emitters ($\varepsilon(\lambda_1) \approx \varepsilon(\lambda_2)$)

Hyp2:Melted particles are spherical or at least very close to be

Hyp3:For a given particle, $\varepsilon(\lambda_i)$ is constant on all its trajectory

Hyp4:All particles have similar $\varepsilon(\lambda_i)$ regardless of their size

6.2 REFERENCE SCHEMATIC



- The blue area represents A_a or A_b
- The clear area on top of the first peak represents the correction (extrapolated additional surface) required to take into account the fact that this particle could not be totally seen in both slits.

6.3 VELOCITY CALCULATION

The velocity measurement is the simplest & precise one carried out by the DPV-2000. The particle velocity v_p is defined as

$$v_p = \frac{s}{TOF} \times \text{Optical magnification of the lens} \quad (1)$$

Since the two-slits photomask is fabricated using microelectronics techniques, s is known at $1\mu\text{m}$ precision. Furthermore, TOF is measured by a high-speed, high precision scope board, and it is as precise as the crystal on the board is. Finally, both s & Optical magnification are passive characteristics that cannot drift with time. The precision on velocity is on the order of 0.5%.

6.4 TEMPERATURE MEASUREMENT

The DPV-2000 is a high-speed, high precision two colors pyrometer. Surface temperature of the particles, T_p , is then measured based on Planck's radiation law. According to this law, the total energy radiated by a spherical particle can be expressed as

$$E(\lambda_i) = \frac{K\varepsilon(\lambda_i)d^2\lambda_i^{-5}}{e^{k_2/\lambda_i T(k)} - 1} \quad (2)$$

Assuming that λ_1 & λ_2 are chosen close enough so that $\varepsilon(\lambda_1) \approx \varepsilon(\lambda_2)$, we can write

$$R = \frac{E(\lambda_1)}{E(\lambda_2)} = \left(\frac{\lambda_1}{\lambda_2}\right)^{-5} e^{\frac{K_2}{T(k)}\left(\frac{1}{\lambda_2} - \frac{1}{\lambda_1}\right)} \quad (3)$$

Taking the natural log of both sides of (3), and solving for $T(k)$, one can easily show that

$$T(k) = \frac{K_2(\lambda_1 - \lambda_2)}{\lambda_1\lambda_2} \left[\frac{1}{\ln R + 5 \ln\left(\frac{\lambda_1}{\lambda_2}\right)} \right] \quad (4)$$

where R was defined in section A. Since temperature is calculated based on a ratio, the shape of the signal does not impact on the value of the ratio, so:

$$R = \frac{E(\lambda_1)}{E(\lambda_2)} = \frac{A_1}{A_2} \tag{5}$$

where A_1 & A_2 were defined in section A.

As long as one stays within the temperature measurement range of the system, the precision on T(k) is 3% or better.

6.5 DIAMETER MEASUREMENT

Using Planck's law & Hyp2, one can write that the diameter of a particle, D_p , is

$$D_p \propto \sqrt{\frac{E(\lambda_i)}{K_3 \varepsilon(\lambda_i)}} \tag{6}$$

where i is 1 or 2. $\varepsilon(\lambda_i)$ being extremely difficult to measure on-line, we define a new coefficient which includes both K_3 & $\varepsilon(\lambda_i)$:

$$DC = K_3 \varepsilon(\lambda_i) \equiv \text{Diameter coefficient}$$

We then rewrite (6) as

$$D_p = \sqrt{\frac{E(\lambda_i)}{DC}} \tag{7}$$

Since diameter is calculated based on energy at ONE wavelength (one channel) only, we must here take into account the fact that some particles will not have perfect horizontal trajectories. The two-peaks signal shown on the schematic is a typical example of a particle partially seen through slit #1 and totally seen through slit #2 ($A_i \neq E_i$). If no correction is applied, this results in a systematic underestimation of the energy radiated by the particle, and consequently, based on (7), this leads to a systematically underestimated diameter value. For all particles showing different peak heights but still accepted because the difference is inferior or equal to the

criteria MAXIMUM PEAK HEIGHTS DIFFERENCE, an ENERGY correction is automatically applied to minimize the error on diameter due to the fact that most of the particles do not travel on horizontal trajectories. We then rewrite (7) as

$$D_p = \sqrt{\frac{E'(\lambda_i)}{DC}} \quad (8)$$

where, again, $E'(\lambda_i)$ is the MEASURED energy CORRECTED for peak height difference.

The correction is of the form

$$E'(\lambda_i) = A_i \left[1 + \frac{(P_1 - P_2)}{2P_1} \right] \quad (9)$$

where P_1 & P_2 are the first and second peak amplitude respectively. Note that values of P_1 & P_2 are generally different at λ_1 as compared to λ_2 , leading to a slightly different correction factor for the two wavelengths.

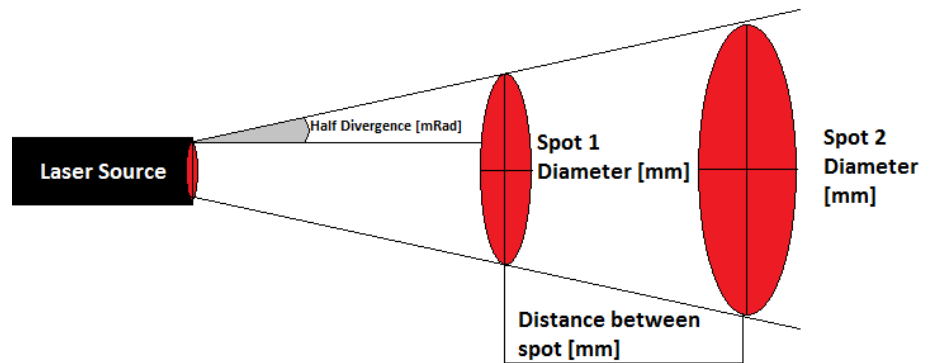
The ENERGY A & ENERGY B values as logged to the *.PRT files were corrected for peak heights difference. This is the reason why we say that ENERGY is the “time integral of the two-peaks curve normalized by velocity AND corrected for peak heights difference”.

It is clear from the above that emissivity $\varepsilon(\lambda_i)$, and thus DC, is an unknown at the beginning of the experiment. To obtain precise ABSOLUTE D_p values, one must follow, for each different material, the calibration procedure described in the reference manual in section 3.5.

When this calibration step is performed, we consider that precision on D_p is between 7 & 15%, and that it is greatly dependent on the validity of the initial hypothesis, specifically Hyp3 concerning sphericity of melted particles.

7. LASER BEAM DIVERGENCE AND LASER POWER

The Beam divergence explains the angular propagation of a laser ray. The unit of the divergence is the milliradian. When the divergence is high, the laser spot will grow faster.

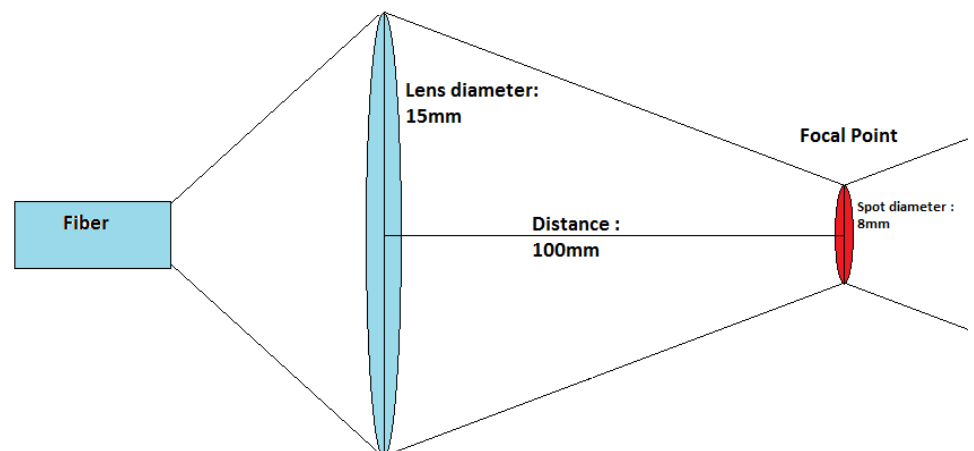


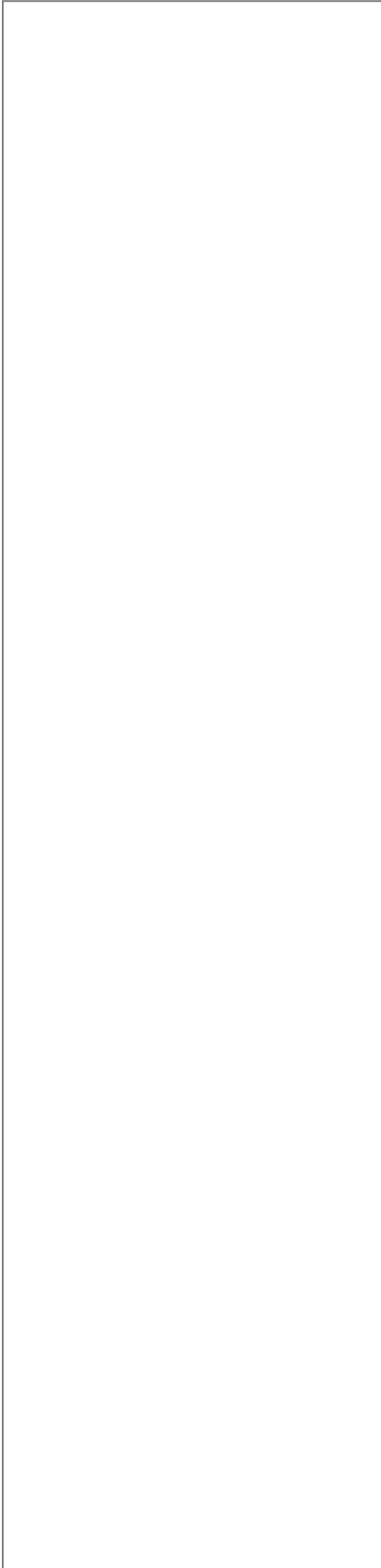
The calculation of the divergence is:

$$Divergence[mrad] = 2 \times \left(\tan^{-1} \left(\frac{Radius2 - Radius1}{Distance} \right) \right)$$

In the Coldspray/ DPV, the light is coupled into an optical fiber before being focused at the working distance. The nominal power of the laser source is 3.3W at the output of the fiber. The divergence after the fiber-lens system is determined by the same calculation.

$$Divergence[mrad] = 2 \times \left(\tan^{-1} \left(\frac{7.5mm - 4mm}{100mm} \right) \right) = 70mrad$$





The power density at the focal point is $6.57W/cm^2$

The Wavelength of the DPV laser is 790nm

8. TROUBLESHOOTING

8.1 HOW TO GET RID OF THE PHANTOM VELOCITY PEAK

It is possible for two out of focus identical particles to cross the measurement volume with such a time shift that they will look like a very symmetrical, lower velocity particle; we refer to this phenomenon as the “phantom velocity peak”. This phantom peak will be more or less important depending on the process. You have two choices here: either you reject particles in post treatment, or you adjust the LOW-SPEED parameter (in the Detection Tuning Screen, see section 1.5.3) high enough to discard those particles right before acquisition.

9. GLOSSARY / ACRONYMS

Item 1	Definition 1
Item 2	Definition 2
Item 3	Definition 3

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11. SERVICE & SUPPORT

Below are the points of contact for questions and/or service-support on DPV-2000/eVOLUTION systems.

TECNAR Automation Ltd (The original manufacturer)

1021, Marie-Victorin Street,

St-Bruno, Qc, Canada, J3V 0M7

Phone: 450-461-1221

Fax:450-461-0808

Email: service@spraysensors.tecnar.com



E C C o n f o r m i t y
D e c l a r a t i o n

Herewith the company:

TECNAR Automation Ltd.

1321, Hocquart Street, St-Bruno, Qc, Canada, J3V 6B5

Declares that the products:

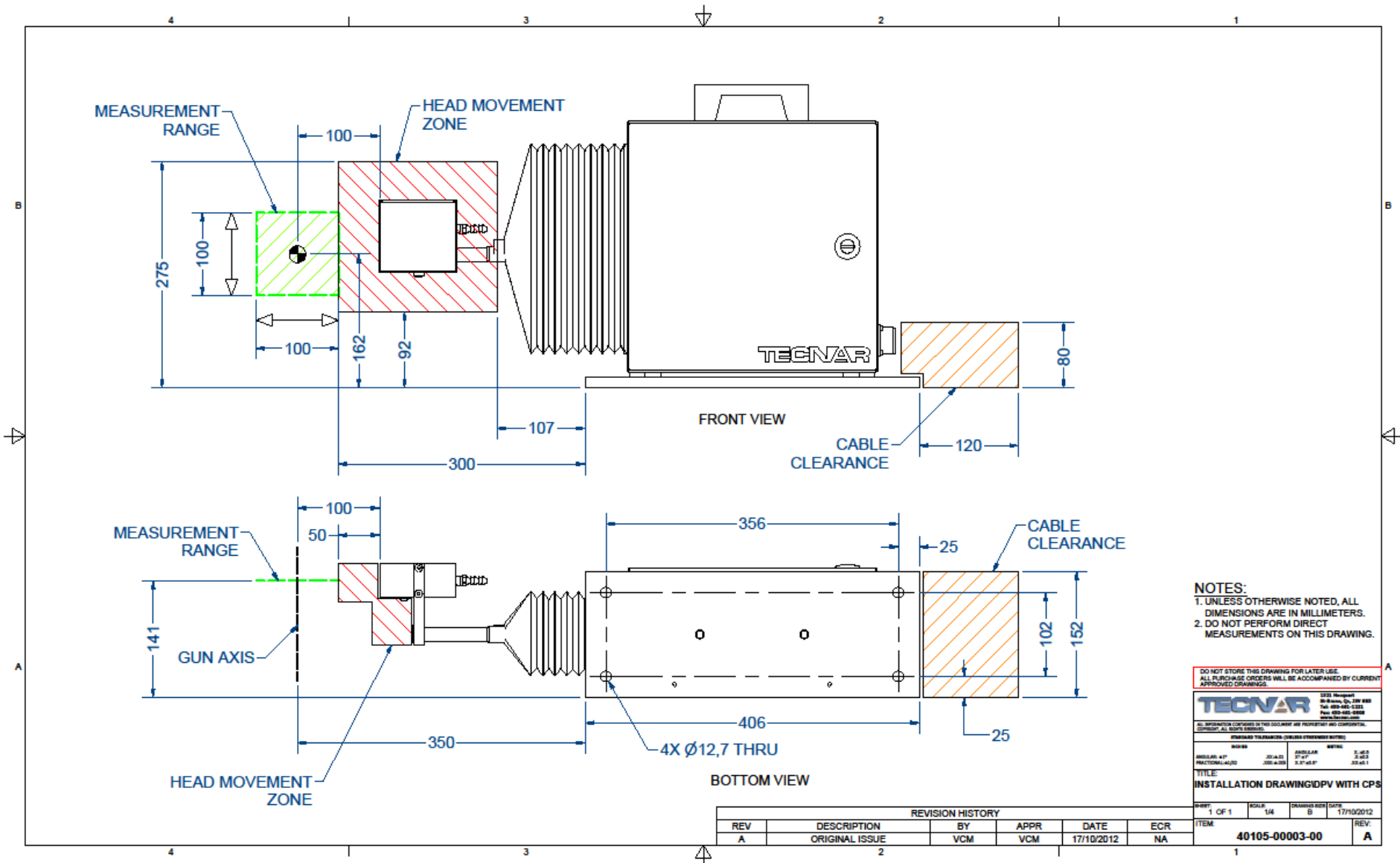
ColdSprayMeter

Meets all the requirements as defined in the following standards:

- CISPR 11: 2009 A1 : 2010
- EN 61000-4-3: 2006 A1: 2008 A2 : 2010
- EN 6100-4-6 : 2009
- EN 6100-4-2 : 2009
- EN 6100-4-4 : 2012
- EN 6100-4-5 : 2006
- EN 6100-4-11 : 2004

St-Bruno, March 1st, 2014

Francois Nadeau
President



NOTES:
 1. UNLESS OTHERWISE NOTED, ALL DIMENSIONS ARE IN MILLIMETERS.
 2. DO NOT PERFORM DIRECT MEASUREMENTS ON THIS DRAWING.

DO NOT STORE THIS DRAWING FOR LATER USE. ALL PURCHASE ORDERS WILL BE ACCOMPANIED BY CURRENT APPROVED DRAWINGS.

TECNAR 2322 Highway 20 Irvine, Ca. 92614 USA Tel: 949-465-0325 Fax: 949-465-0300 www.tecnar.com

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FORMER: FORMER (2008) (REVISED 2012)

REVISED	DATE	BY	APPR	DATE	ECR
REVISED	2012-10-17	VCM	VCM	2012-10-17	NA

TITLE: INSTALLATION DRAWING/DPV WITH CPS

REVISION HISTORY					
REV	DESCRIPTION	BY	APPR	DATE	ECR
A	ORIGINAL ISSUE	VCM	VCM	17/10/2012	NA

SHEET: 1 OF 1 SCALE: 1/4" = 1" DRAWING NO: 40105-00003-00 DATE: 17/10/2012 REV: A

FIGURE 27 DPV EVOLUTION INSTALLATION DRAWING